

Design and game-theoretical analysis of community-based market mechanisms in heat and electricity systems

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Abstract

In an increasingly decentralized energy system with tight interdependencies with heat and electricity markets, prosumers, who act both as consumers and producers at the interface between the markets, are becoming important operational flexibility providers. Policy-makers and market operators need a better understanding of the motivations and behavior of prosumers in order to harness their underlying flexibility. In that context, existing market mechanisms must be accompanied by decision-making tools which enable direct participation of prosumers and cooperation among them towards a social choice. This work focuses on designing a *community-based* market mechanism, in which prosumers can pool their heat and electricity production and consumption, and coordinate their participation in heat and electricity wholesale markets. A central research question that is addressed, is to understand how this mechanism can affect the outcomes of the interactions among individuals towards a social choice, and in particular incentivize cooperation among prosumers. Game-theoretical concepts are used to analyze the properties of the proposed market mechanism with different allocation schemes, namely uniform pricing, Vickrey-Clarke-Groves, Shapley value, and nucleolus. This analysis shows that it is beneficial for the community as a whole to cooperate and that there exists a set of stable allocations for the proposed mechanism. Additionally, although no allocation can satisfy all the fundamental desirable market properties, this study demonstrates that the proposed mechanism based on a nucleolus allocation can provide an interesting trade-off between *stability*, *efficiency*, and *incentive compatibility*. Finally, the concepts and properties discussed in this work are illustrated in a case study.

Keywords: community-based market; multi-carrier energy system; mechanism design; game theory

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1. Introduction

Worldwide, the energy transition towards a more environmentally friendly and sustainable energy system has led to an unprecedented share of the generation mix being covered by renewable production (Chu & Majumdar, 2012; Lund, 2007; Chu et al., 2017). Managing these large shares of decentralized, stochastic, and non-dispatchable production has increased the need for operational flexibility¹ in power systems (Morales et al., 2013).

In addition to the traditional sources of operational flexibility, such as dispatchable thermal power plants and electricity storage, flexibility in power systems may come from the interfacing and coordination with other energy systems, in particular the heat system (Lund, 2005; Lund et al., 2010, 2014; Meibom et al., 2013; Münster et al., 2012; Lund et al., 2015a; Wang et al., 2017c). At the wholesale level, harnessing this operational flexibility requires the design of new markets and trading mechanisms that model and exploit the interactions between the systems (Mitridati & Pinson, 2016; Pinson et al., 2017).

In the meantime, a more profound and fundamental shift is happening in heat and electricity systems due to a change from a top-down energy system management approach to a decentralized approach (Bouffard & Kirschen, 2008). Motivated by growing environmental concerns and social commitment (Goulden et al., 2014; Gangale et al., 2013), a new category of energy users, also called *prosumers*, who may consume, produce, store, and share energy, has emerged as central and proactive energy market participants. In dense urban areas, where electricity and district heating infrastructures cohabit, prosumers interface both energy systems. It is expected that harnessing their operational flexibility can induce a soft coordination between the systems and benefit the overall energy system, in terms of social welfare and sustainability (Wang et al., 2017b; Geidl et al., 2007; Lund et al., 2015b). Kirschen (2003) provides an overview of the potential benefits of better accounting for demand-side flexibility in future wholesale market designs. In addition, O’Connell et al. (2016), Liu et al. (2015), and Bobo et al. (2018) highlight the need for new trading mechanisms, such as flexibility-oriented products and extended bid formats, that facilitate market access to prosumers, and reveal the value of their operational flexibility in a market environment. Additionally, policy-makers and market operators lack a better understanding of the motivations and behavior of prosumers to effectively and efficiently integrate them into electricity markets (Stern, 1992; Allcott & Mullainathan, 2010; Gyamfi et al., 2013; Da Silva et al., 2012; Lampropoulos et al., 2010). In that context, the aforementioned top-down market solutions should be accompanied by *consumer-centric* decision-making tools, which enable prosumers to directly manage their energy consumption and production. Parag & Sovacool (2016) and Sousa et al. (2018) identify and discuss different potential consumer-centric market mechanisms. By opposition with top-down demand-response programs, consumer-centric market mechanisms focus on motivating direct participation from the prosumers, and provide a framework that coordinates the outcomes of interactions among them towards a social choice (Haring et al., 2016). The motivation behind this approach is to take advantage of under-utilized sources of flexibility and synergies among prosumers, not unlike the concept of sharing-economy in other industry sectors (Kalathil et al., 2017; Heinrichs, 2013). Kalkbrenner & Roosen (2016) and Klein & Coffey (2016) highlight how local energy communities can increase social acceptance and motivation to participate in demand response programs, compared to traditional top-down approaches.

¹The term operational flexibility, or simply flexibility, is traditionally defined as the capability of a system to modify its output or state in response to a signal (Zhao et al., 2016).

The increasingly decentralized energy systems highlight the need for consumer-centric market mechanisms aiming at harnessing the flexibility of prosumers across multiple energy carriers, namely heat and electricity. The design and analysis of such mechanisms raise two conceptual research questions.

First, what value can a group of prosumers achieve by exploiting the flexibility and synergies of different types of loads? The term of *value* is understood in a game-theoretical context as the increase in social welfare that a group of prosumers can achieve by cooperating rather than standing alone (Peters, 2015). This value represents the benefits for the community as a whole when prosumers collaborate. In a multi-carrier energy system, this value arises from exploiting the flexibility of prosumers and the synergies among different types of loads. In particular, fuel-shift technologies, such as heat pumps (HPs) and micro combined heat and power plants (CHPs), in heat and electricity markets have been shown to be important sources of cross-carrier flexibility (Wang et al., 2017a; Alimohammadisagvand et al., 2016; De Paepe et al., 2006; Houwing et al., 2011). In addition, modeling and exploiting the thermal storage capacity of buildings greatly increase the operational flexibility of prosumers and their ability to provide demand response in both heat and electricity systems (Good & Mancarella, 2017; Alimohammadisagvand et al., 2016; Dominković et al., 2018). From an economic perspective, valuing the flexibility of different types of loads, such as district heating and electricity consumption of heat pumps, requires modeling their synergies. Various studies have proposed community-based control strategies for the energy management of building that model these technical and economic aspects (Brahman et al., 2015; Good & Mancarella, 2017; Wang et al., 2018; Darivianakis et al., 2015, 2017b). In particular, Shaikh et al. (2014) and Klein et al. (2012) propose control strategies for buildings based on the utility that prosumers derive from the indoor temperature, rather than the energy carrier consumed. These operational models highlight the potential benefits of cooperating and provide operational models to achieve that value (Alam et al., 2013; Wang et al., 2017a). This raises a second conceptual question.

How to design a consumer-centric market mechanism that incentivizes prosumers to collaborate towards this social optimum? An *efficient* community-based market mechanism should aim at coordinating the energy production and consumption of a group of prosumers towards a social optimum, i.e. a maximum social welfare for the community as a whole. Achieving this value in a market environment requires designing institutions and trading mechanisms that accurately model the physical and economic characteristics of each agent, and facilitate interactions between them. However, commonly-used bid formats, such as price-quantity and block bids, are not adequate to accurately model the strong dependencies across multiple time steps and energy carriers. Various studies have suggested that extending standard price-quantity bids could help reveal the flexibility of prosumers (Liu et al., 2015). Yet, no such a bid format has been proposed for multi-carrier energy systems. Furthermore, a consumer-centric approach must ensure that prosumers are voluntarily participating in the proposed mechanism, and are satisfied with the outcomes. Such a mechanism is called *stable*. Beyond the concept of value for the community as a whole, this raises the issue of the *fair* allocation of this value among the prosumers. Addressing this question requires modeling the outcomes of this mechanism, as well as the behavior and interactions among the agents through game-theoretical models (Roth, 2000). A series of recent studies have adopted a consumer-centric approach for prosumers in electricity markets (Morstyn et al., 2018a; Sorin et al., 2018; Haring et al., 2016; Moret & Pinson, 2018), but has failed to provide a thorough analysis of the properties of these mechanisms. Han et al. (2018) and Tushar et al. (2018) propose a cooperative game-

theoretical analysis of the efficiency and fairness of a community-based market mechanism for energy management. However, these studies assume complete information on the preferences of each agent, which is quite restrictive. Ensuring the truthful participation of agents with privately known preferences, i.e. *incentive compatibility*, is a central research question in the field mechanism design (Hurwicz, 1972). However, a gap remains in analyzing the link and trade-off between incentive compatibility, efficiency, and stability of consumer-centric market mechanisms.

The main objective of this work is to design a consumer-centric market mechanism that incentivizes prosumers in a multi-carrier energy system to collaborate to optimize the energy management of the community. In view of the existing literature, this work makes several applied and theoretical contributions to the state of the art. From an applied perspective, we design a novel community-based market mechanism, in which prosumers can pool their heat and electricity production and consumption, and coordinate their participation in heat and electricity wholesale markets. The proposed market mechanism provides adequate institutions and trading mechanisms to reflect the physical and economic aspects of the flexibility of prosumers at the interface between heat and electricity systems. From a theoretical perspective, we demonstrate two fundamental properties of the proposed community-based market mechanism through game-theoretical models. We first demonstrate that there exists a non-empty set of stabilizing allocations for the proposed mechanism. We then demonstrate that the particular structure of the proposed mechanism provides an interesting trade-off between the properties of incentive compatibility, efficiency, and stability. Finally, we analyze the properties of this community-based market mechanism for different allocation mechanisms, namely uniform pricing, Vickrey-Clarke-Groves (VCG), Shapley value, and nucleolus. While it is known that, among these allocations, solely the nucleolus allocation provides a stabilizing mechanism in the general case, we demonstrate that, under the assumption of perfect competition among the prosumers, the uniform pricing allocation is also stabilizing.

The remainder of this paper is organized as follows. Section 2 introduces the general framework and theoretical background for the design and analysis of consumer-centric market mechanisms. Section 3 presents in details the proposed mechanism, along with different allocation mechanisms. Section 4 analyzes the properties of the resulting mechanisms. Section 5 illustrates the theoretical findings of this work using a case study. Finally, Section 6 presents the conclusions and discussions.

2. Status quo on consumer-centric market mechanism design

This section presents an overview of the literature on consumer-centric market mechanisms for energy management and lays the foundation for the proposed approach. Additionally, for the sake of self-containment, general concepts related to the field of mechanism design, and game-theoretical models are presented in order to formulate and analyze the properties of the proposed mechanism.

2.1. Consumer-centric market mechanisms in energy systems

Traditionally, the operational flexibility of residential prosumers is being harnessed by entities, the so-called *aggregators*, who are profit-maximizers, and centrally manage a group of loads via direct control (Wang & Deng, 2018) or indirect price signals (Callaway & Hiskens, 2011). Koch & Piette (2009) provides an overview of the relative benefits of direct and indirect load control programs. While these approaches are designed to provide incentives and elicit demand response from prosumers, they still suffer from various economic, regulatory, technological, and social barrier (O’Connell et al., 2014; Vallés et al., 2016; Good et al., 2017; Medina et al., 2010). In particular,

these centralized mechanisms for demand response fail to motivate cooperation among prosumers, and exploit the synergies across different types of prosumers and load (Haring et al., 2016).

Contrary to centralized demand response mechanisms, in which a profit-maximizing aggregator controls a group of loads via prices or direct signals, decentralized mechanisms, also referred to as *consumer-centric* approaches, provide a framework in which consumers act cooperatively to exchange energy, and aggregate their flexibility (Haring et al., 2016). Parag & Sovacool (2016) provides an overview of different consumer-centric market mechanisms. Consumer-centric approaches can broadly be divided into *peer-to-peer* and *community-based* mechanisms, as illustrated in Figure 1. In a peer-to-peer mechanism, prosumers communicate directly with one another and trade their energy via bilateral contracts and agreement (Morstyn et al., 2018b). This approach raises issues of communication and convergence towards a social choice. In community-based market mechanisms, the information from all prosumers is gathered by a so-called *community manager* that seeks to maximize the social welfare of the community, i.e., the sum of the individual utilities of all agents (Moret et al., 2018; Morstyn et al., 2018a; Sorin et al., 2018).

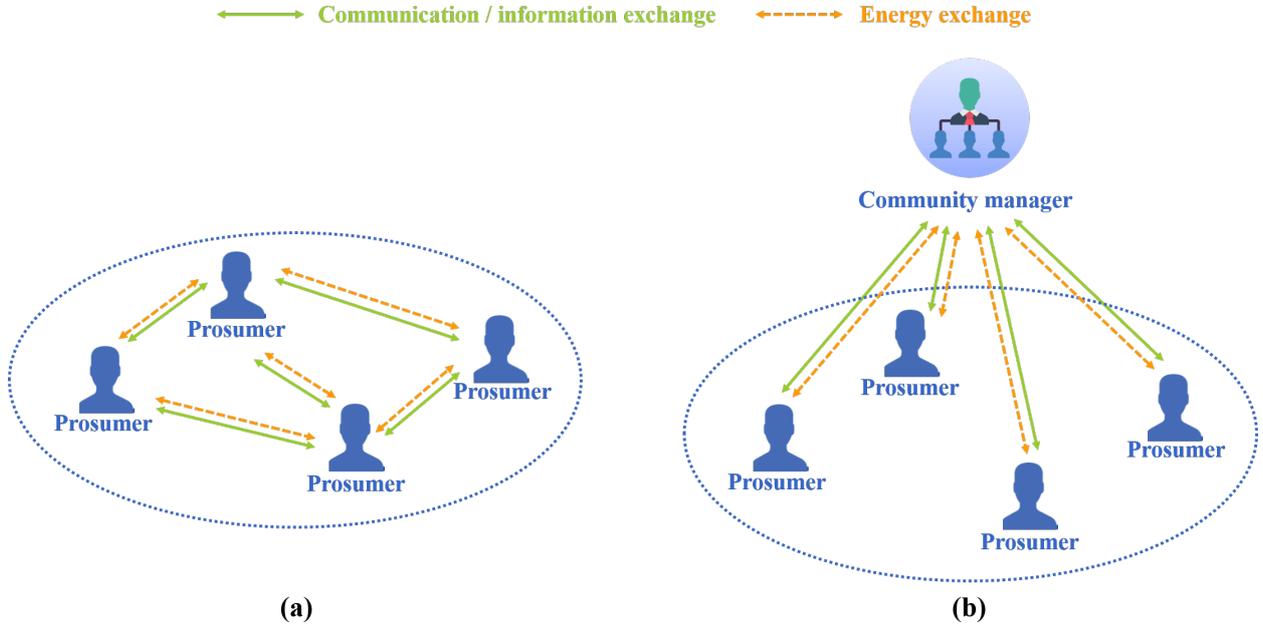


Figure 1: Organization of consumer-centric market mechanisms: (a) peer-to-peer, and (b) community-based.

This study focuses on designing a community-based market mechanism, in which prosumers can pool their heat and electricity production and consumption, and coordinate their participation in heat and electricity wholesale markets. Each prosumer $j \in \mathcal{N}$ in this community holds private information on its true preferences. The community manager elicits information from the prosumers, and based on this information, aims at maximizing the social welfare of the community by solving an energy management problem. Once an optimal strategy for the community has been identified, the community manager computes the value of this cooperation and derives a payment rule that redistributes this value. The community manager in this mechanism complies with the following three general steps:

1. Elicit information from individual agents, i.e., prosumers in the community, on their prefer-

ences, represented by the matrix $\mathcal{B} = [\mathcal{B}_1, \dots, \mathcal{B}_N] \in \mathbb{R}^{K_1 \times N}$, where each column $\mathcal{B}_j \in \mathbb{R}^{K_1}$ represents the vector of preferences of a prosumer $j \in \mathcal{N}$. For notational simplicity, the dimension K_1 represents the length of the vector of preferences of the prosumers, which includes their load utilities, production costs, and technical parameters of their building and assets over all hours $t \in \mathcal{T}$ of the day.

2. Determine the optimal energy dispatch and procurement strategy $X^{\mathcal{N}^*}(\mathcal{B}) \in \mathbb{R}^{K_2 \times N}$ that maximizes the social welfare of the community with respect to the revealed preferences \mathcal{B} , where each column $X_j^{\mathcal{N}^*}(\mathcal{B}) \in \mathbb{R}^{K_2}$ represents the vector of optimal decisions of a prosumer $j \in \mathcal{N}$. For notational simplicity, the dimension K_2 represents the length of the vector of decision variables of the prosumers, which includes their energy dispatch, exchanges with the grid and within the community, and state of their system over all hours $t \in \mathcal{T}$ of the day.
3. Given the optimal energy management strategy and the revealed preferences, derive the payment rule $\mathcal{P}(X^{\mathcal{N}^*}(\mathcal{B})) \in \mathbb{R}^N$, whose entries $\mathcal{P}_j(X^{\mathcal{N}^*}(\mathcal{B}))$ represent the revenue (if $\mathcal{P}_j(X^{\mathcal{N}^*}(\mathcal{B})) \geq 0$) or payment (if $\mathcal{P}_j(X^{\mathcal{N}^*}(\mathcal{B})) \leq 0$) of each prosumer $j \in \mathcal{N}$.

The outcomes of this mechanism are represented by the pair $(X^{\mathcal{N}^*}(\mathcal{B}), \mathcal{P}(X^{\mathcal{N}^*}(\mathcal{B})))$ with respect to the revealed preferences \mathcal{B} . A description of the optimization variables and preference matrices, all well as their dimensions, will be provided in [Appendix A](#) and [Appendix B](#). This mechanism is similar to a so-called indirect mechanism described in [Nisan et al. \(2007\)](#); [Khazaei & Zhao \(2018\)](#).

The proposed consumer-centric market mechanism must provide institutions and trading mechanisms that take into consideration the physical and economic characteristics of the prosumers at the interface between heat and electricity systems. These characteristics can be represented by the bids \mathcal{B} . Additionally, the outcomes of the proposed mechanism $(X^{\mathcal{N}^*}(\mathcal{B}), \mathcal{P}(X^{\mathcal{N}^*}(\mathcal{B})))$ must guarantee certain desirable properties in order to ensure cooperation among the prosumers. The structure of the bids \mathcal{B} , the energy management problem of the community manager, and the form of the payment rule $\mathcal{P}(X^{\mathcal{N}^*}(\mathcal{B}))$, as well as the properties of the resulting mechanism will be discussed in the remainder of this study.

2.2. Mechanism design

The field of mechanism design provides a framework to design rules and institutions that coordinate the interactions between self-interested agents, and analyze the outcomes of these interactions. The interested reader is referred to [Hurwicz \(1973\)](#), [Silva et al. \(2001\)](#), [Vulkan et al. \(2013\)](#) and [Hurwicz & Reiter \(2006\)](#) for an introduction to the theory of mechanism design. The central question that must be addressed when designing any mechanism, is how the proposed rules and institutions impact the interactions among the agents. In other words, what properties does the proposed mechanism satisfy? The following describes a number of desirable properties, analyzed in the context of a community-based market mechanism with decentralized information.

As by design the proposed consumer-centric market mechanism seeks to maximize the true social welfare of the energy community, it should satisfy the fundamental *efficiency* property².

Property 1 (Efficiency). *The social welfare of the agents participating in the mechanism, with respect to the revealed preferences \mathcal{B} , is maximized, and no agent desires to deviate unilaterally from its dispatch. In other words, the outcomes of social welfare maximization align with profit-maximization of agents.*

²Note that the concept of efficiency is defined with respect to the revealed preferences rather than the true preferences.

This property is essential to guarantee that the community as a whole, benefits from cooperating. Indeed, it guarantees that the outcomes of social welfare maximization align with the maximization of the private utilities of the agents. Furthermore, the true social welfare of the community is maximized, and the true value of cooperating is achieved in case the agents are truthful, i.e., reveal their true preferences. As the agents hold private information, they might have incentives to misreport their true preferences in order to manipulate the outcomes of the community management problem and increase their profits, or for privacy concerns. Thus, designing a mechanism that motivates the agents to be truthful is a major challenge for the community manager. Such a property is referred to as *incentive compatibility*.

Property 2 (Incentive compatibility). *Every agent can maximize its utility by acting according to its true preferences.*

Furthermore, in order to ensure social acceptance, a consumer-centric market mechanism should ensure that the outcomes of the mechanism are considered *fair* by all agents. Various definitions of fairness in mechanism design have been used in the literature. In this study, it is used in the sense of a *stable* allocation mechanism that ensures that all agents are satisfied with the outcomes of the mechanism and do not wish to split from the community. Tushar et al. (2018) links the social acceptance of a consumer-centric market mechanism to this stability property, using behavioral economy theory. For that purpose, two essential properties are *budget balance* and *group rationality*.

Property 3 (Budget balance (allocation efficiency)). *The community manager has neither financial deficit nor financial excess.*

This property ensures that the community manager redistributes the entire benefits, or losses, among the prosumers. In this context, it is particularly important as it guarantees that the community manager is non-profit.

Property 4 (Group rationality). *No group of agents can benefit from splitting from the community.*

As no individual agent or group of agents can benefit from splitting from the community, this property guarantees that the outcomes of the mechanism are stable. These two properties will be formally defined in Section 2.3, within the conceptual framework of cooperative game theory.

A mechanism satisfying Properties 1 - 4 ensures that the private utilities of the agents are aggregated to achieve a social choice. In the context of the proposed community-based market mechanism, these properties incentivize prosumers to collaborate to maximize the social welfare of the community. An in-depth analysis of these properties for different mechanisms will be provided in Section 4. However, a fundamental result states that no mechanism with decentralized information can guarantee simultaneously efficiency, incentive compatibility, budget balance, as well as cost recovery for all agents Hurwicz (1972); Myerson & Satterthwaite (1983). Similarly, Roth (1982) states that no mechanism can guarantee incentive compatibility, efficiency, budget balance, and group rationality. Thus, a major design challenge which is addressed in this study is to identify the links and the trade-off between these properties.

2.3. Game-theoretical tools

Analyzing the properties of a given mechanism requires modeling the outcomes of this mechanism, as well as the behavior of the agents and the interactions between them. The literature on mechanism design relies on cooperative and non-cooperative game-theoretical tools to do so

(Roth, 2000). The main distinction between cooperative and non-cooperative game theory is in the modeling technique that is used. Non-cooperative game theory provides an explicit model of the behavior and interactions among the agents, whereas cooperative game theory provides an abstract representation of the agents through the outcomes and payoffs that they can reach (Peters, 2015; Saad et al., 2009; Osborne & Rubinstein, 1994; Nisan et al., 2007). Although cooperative and non-cooperative game-theoretical tools rely on different modeling techniques, they are both used to answer the same central question, i.e., what is the impact of the institutions and rules imposed by a mechanism on the behavior of the agents and interactions between them? Therefore, this section revisits the properties introduced in Section 2.2 under both cooperative and non-cooperative game-theoretical frameworks.

2.3.1. Cooperative game theory

The starting point of a cooperative game-theoretical analysis of a mechanism, is to define the value $v^{\mathcal{S}}(\mathcal{B})$ with respect to the revealed preferences \mathcal{B} , that can be achieved by a group of agents forming a *coalition* $\mathcal{S} \in 2^{\mathcal{N}}$, where $2^{\mathcal{N}}$ represents the set of all coalitions included in the grand-coalition \mathcal{N} . In particular, in the community-based market mechanism considered, the value of a coalition is defined as the increase in social welfare, compared to the case where all agents in the coalition optimize their energy management strategy alone. The coalitional game form of a mechanism is defined as follows.

Definition 1 (Coalitional game form). *The pair $(\mathcal{N}, v(\mathcal{B}))$ defines a cooperative game if and only if the value function $v(\mathcal{B}) : \mathcal{S} \in 2^{\mathcal{N}} \mapsto v^{\mathcal{S}}(\mathcal{B}) \in \mathbb{R}^+$ satisfies*

1. $v^{\emptyset}(\mathcal{B}) = 0$, i.e., the value of an empty coalition is null.
2. For any two selected coalitions $\mathcal{S} \in 2^{\mathcal{N}}, \mathcal{V} \in 2^{\mathcal{N}}$, such that $\mathcal{S} \cap \mathcal{V} = \emptyset$ super-additivity holds, i.e., $v^{\mathcal{S}}(\mathcal{B}) + v^{\mathcal{V}}(\mathcal{B}) \leq v^{\mathcal{S} \cup \mathcal{V}}(\mathcal{B})$.

Super-additivity implies that the value of any coalition cannot be improved by splitting it into smaller coalitions. In practice, this guarantees that overall it is beneficial to form the grand-coalition \mathcal{N} , rather than collaborating in smaller coalitions $\mathcal{S} \in 2^{\mathcal{N}}$, or standing alone. However, it does not guarantee that all agents benefit individually from joining the grand-coalition, and are satisfied with the outcomes of the proposed mechanism. This raises the issue of a fair redistribution of this value through the design of an allocation mechanism. The allocation mechanism of a cooperative game can be directly expressed as a function of the payment rule of the corresponding mechanism. Therefore, the notions of allocation and payment, though different, can be used equivalently to describe the outcomes of a mechanism and its properties. The vector of allocations $\pi(X^{\mathcal{N}^*}(\mathcal{B})) \in \mathbb{R}^{\mathcal{N}}$, whose entries $\pi_j(X^{\mathcal{N}^*}(\mathcal{B}))$ represent the share of the value $v^{\mathcal{N}}(\mathcal{B})$ allocated to an agent $j \in \mathcal{N}$.

In this cooperative game-theoretical framework, the budget balance (or efficient allocation) property of the proposed community-based market mechanism introduced in Definition 3 rewrites

$$\sum_{j \in \mathcal{N}} \pi_j(X^{\mathcal{N}^*}(\mathcal{B})) = v^{\mathcal{N}}(\mathcal{B}). \quad (1)$$

This ensures that the entire value of the coalition, i.e., the increase in social welfare, is allocated to the agents. Additionally, in order to measure the satisfaction of agents in the grand-coalition \mathcal{N} , with respect to an allocation $\pi(X^{\mathcal{N}^*}(\mathcal{B}))$, we define the *excess of a coalition* as follows.

Definition 2 (Excess). *The excess $\epsilon(\pi(X^{\mathcal{N}^*}(\mathcal{B}))) \in \mathbb{R}^{2^{\mathcal{N}}-2}$ is a vector whose entries*

$$\epsilon_{\mathcal{S}}\left(\pi\left(X^{\mathcal{N}^*}(\mathcal{B})\right)\right) = v^{\mathcal{S}}(\mathcal{B}) - \sum_{j \in \mathcal{S}} \pi_j\left(X^{\mathcal{N}^*}(\mathcal{B})\right), \quad (2)$$

represent the dissatisfaction of the coalition $\mathcal{S} \in 2^{\mathcal{N}} \setminus \{\mathcal{N}, \emptyset\}$ with respect to the allocation $\pi(X^{\mathcal{N}^}(\mathcal{B}))$, arranged in decreasing order.*

By construction, the excess of the grand-coalition or an empty coalition would be equal to zero for any efficient allocation $\pi(X^{\mathcal{N}^*}(\mathcal{B})) \in \mathcal{I}(v(\mathcal{B}))$, but this is not necessarily true for other coalitions $\mathcal{S} \in 2^{\mathcal{N}} \setminus \{\mathcal{N}, \emptyset\}$. In fact, if $\epsilon_{\mathcal{S}}(\pi(X^{\mathcal{N}^*}(\mathcal{B}))) > 0$, the agents in the coalition $\mathcal{S} \in 2^{\mathcal{N}} \setminus \{\mathcal{N}, \emptyset\}$ can achieve higher profits by leaving the grand-coalition \mathcal{N} . In that context, a cooperative game-theoretical interpretation of the group rationality property is the set of allocations that guarantee non-positive excesses for all coalitions $\mathcal{S} \in 2^{\mathcal{N}} \setminus \{\mathcal{N}, \emptyset\}$. Let us define the *revealed core* $\mathcal{C}(\mathcal{N}, v(\mathcal{B}))$ of the cooperative game $\mathcal{N}, v(\mathcal{B})$ as the set of efficient allocation mechanisms that respect group rationality, i.e., such that

Definition 3 (Revealed core). *The revealed core $\mathcal{C}(\mathcal{N}, v(\mathcal{B}))$ of a cooperative game is defined as the set of allocations such that no coalition $\mathcal{S} \in 2^{\mathcal{N}} \setminus \{\mathcal{N}, \emptyset\}$ has a positive excess with respect to any of those allocations, i.e., $\mathcal{C}(\mathcal{N}, v(\mathcal{B})) = \{\pi(X^{\mathcal{N}^*}(\mathcal{B})) \in \mathcal{I}(v(\mathcal{B})) \mid \epsilon_{\mathcal{S}}(\pi(X^{\mathcal{N}^*}(\mathcal{B}))) \leq 0, \forall \mathcal{S} \in 2^{\mathcal{N}} \setminus \{\mathcal{N}, \emptyset\}\}$.*

Thus, a so-called *core-selecting* mechanism that systematically selects an allocation that is in the revealed core of the cooperative game is considered fair by the agents participating in this mechanism, and is referred to as a *stabilizing* mechanism (Day & Milgrom, 2008).

Definition 4 (Core-selecting mechanism). *A core-selecting mechanism selects, for any revealed preferences \mathcal{B} , a dispatch $X^{\mathcal{N}^*}(\mathcal{B})$ and an allocation $\pi(X^{\mathcal{N}^*}(\mathcal{B}))$ in the revealed core $\mathcal{C}(\mathcal{N}, v(\mathcal{B}))$ of the cooperative game $(\mathcal{N}, v(\mathcal{B}))$.*

Note that, the main concepts of cooperative game theory are defined with respect to the revealed preferences \mathcal{B} . However, cooperative game-theoretical tools do not provide an explicit model of the decisions of individual agents. Therefore, non-cooperative game theory can expand the scope of this analysis and provide a framework to study the incentive compatibility of the proposed mechanism.

2.3.2. Non-cooperative game theory

Non-cooperative game theory provides tools to analyze the decisions and interactions among the agents in a mechanism. In a game-theoretical framework, the vector of revealed preferences \mathcal{B}_j of any agent $j \in \mathcal{N}$ is also referred to as its *strategy*. The most commonly used concept in non-cooperative game theory is the *Nash equilibrium*, which guarantees that the strategy \mathcal{B}_j of each agent $j \in \mathcal{N}$ is optimal with respect to the strategies \mathcal{B}_{-j} of the other agents $k \in \mathcal{N} \setminus \{j\}$, i.e., no agent can benefit from unilaterally deviating from the equilibrium outcome (Maskin, 1999). Therefore, the efficiency property can be interpreted as the existence of a Nash equilibrium that coincides with the maximum social welfare, i.e., a *Pareto efficient* Nash equilibrium.

A stronger concept is the *dominant-strategy equilibrium*, which guarantees that the strategy of each agent is optimal, regardless of the strategies of the other agents. Any dominant-strategy equilibrium is a Nash equilibrium. The incentive compatibility property, also called *dominant-strategy*

incentive compatibility, requires that there exists a truth-revealing dominant-strategy equilibrium, i.e. each agent can achieve its optimal objective, regardless of what the others do, by revealing its true preferences. In other words, this guarantees that no agent can benefit from manipulating the outcomes of the mechanism by misreporting its true preferences. Therefore, this property is central in mechanisms with decentralized information.

2.3.3. Link between stability, efficiency, and incentive compatibility

The notion of revealed core in cooperative game theory has a clear interpretation in non-cooperative game theory and equilibrium. Indeed, Karaca et al. (2018) shows that a mechanism is *coalition-proof*, in the sense that it prevents shill bidding, i.e., bidding under multiple identities, and collusion, if and only if it is a core-selecting mechanism. In other words, the notion of revealed core is directly linked to the *coalition-proof Nash equilibrium* concept introduced in Bernheim et al. (1987) and Bernheim & Whinston (1987), which ensures that a Nash equilibrium is immune not only to individual deviations but also to self-enforcing coalitional deviations.

Furthermore, while it is known that there exists no dominant-strategy incentive compatible, efficient, and stabilizing mechanism (Roth, 1982), Day & Milgrom (2008) investigates the trade-off between these three properties by introducing a weaker version of the dominant-strategy incentive compatibility property, called *Incentive optimality*, which minimizes incentives to deviate from a truth-revealing strategy.

Definition 5 (Incentive profile). *The incentive profile $\mu^\pi(\mathcal{B}) \in \mathbb{R}^N$ of a core-selecting mechanism $(X^{\mathcal{N}^*}(\mathcal{B}), \pi(X^{\mathcal{N}^*}(\mathcal{B})))$ at the revealed preferences \mathcal{B} , defines the maximum gain for each agent $j \in \mathcal{N}$ from unilaterally deviating from this strategy, i.e., $\mu_j^\pi(\mathcal{B}) = \sup_{\hat{\mathcal{B}}_j} \pi_j(X^{\mathcal{N}^*}(\hat{\mathcal{B}}_j, \mathcal{B}_{-j}))$, $\forall j \in \mathcal{N}$.*

Property 5 (Incentive optimality). *A core-selecting mechanism (X, p) provides optimal incentives at the revealed preferences \mathcal{B} if there exists no other core-selecting mechanism (X, \hat{p}) that has a lower incentive profile at \mathcal{B} , i.e., such that $\mu_j^{\hat{\pi}}(\mathcal{B}) \leq \mu_j^\pi(\mathcal{B})$, $\forall j \in \mathcal{N}$, with a strict inequality for at least one agent $j \in \mathcal{N}$. In particular, a core-selecting mechanism is incentive-optimal if it provides optimal incentives at any revealed preferences \mathcal{B} .*

A fundamental theorem introduced by Day & Milgrom (2008) states that a core-selecting mechanism is incentive-optimal if and only if for any revealed preferences \mathcal{B} it chooses an allocation $\pi(X^{\mathcal{N}^*}(\mathcal{B}))$ that is Pareto efficient for the agents. In other words, if there is no other allocation in the revealed core $\hat{\pi}(\mathcal{B}) \in \mathcal{C}(\mathcal{N}, v(\mathcal{B}))$ that dominates it, i.e., such that $\hat{\pi}_j(\mathcal{B}) \geq \pi_j(X^{\mathcal{N}^*}(\mathcal{B}))$, $\forall j \in \mathcal{N}$ with strict inequality for at least one prosumer.

3. Proposed community-based market mechanism for energy management in heat and electricity systems

In the proposed community-based market mechanism, a group of prosumers can pool their heat and electricity production and consumption, and coordinate their participation in heat and electricity wholesale markets, over each hour of the following day. This section introduces the different steps of the proposed mechanism. First, the individual agents, i.e., prosumers in the community, and their private information \mathcal{B} are described. We then introduce the mathematical formulation of the optimal energy management problem solved by the community manager. Finally, different

payment rules and allocation mechanisms are presented. For brevity, this section introduces a compact form of these models. The mathematical models representing the operating constraints of the prosumers, and the optimization problem of the community manager are detailed in [Appendix B](#).

3.1. Model of individual agents with private information

Individual agents participating in the proposed mechanism are prosumers at the interface between heat and electricity systems. As illustrated in [Figure 2](#), for each prosumer $j \in \mathcal{N}$, we can distinguish four main types of flexible loads over all hours $t \in \mathcal{T}$ of the day, namely space heating, domestic hot water consumption, electricity load of heat pump, and other electrical appliances. In order to model the flexibility of space heating loads, the temperature dynamics of the buildings are represented through a set of linear equations detailed in [Appendix B](#). The utility derived from space heating is defined with respect to a vector of temperature comfort level $T_j^{\text{set}} \in \mathbb{R}^T$ and flexibility range $\bar{u}_j^{\text{up}} \in \mathbb{R}_+^T$, $\bar{u}_j^{\text{down}} \in \mathbb{R}_+^T$ preferences. It can be supplied by district heating, electricity (via heat pumps), or heat storage tanks.

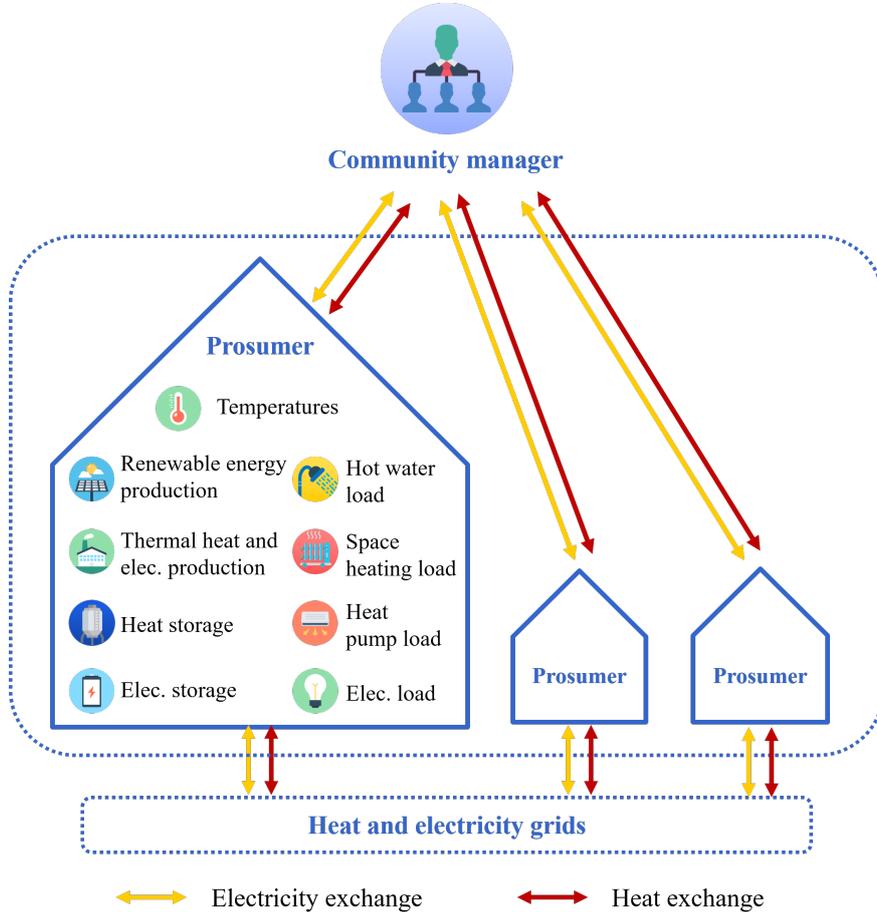


Figure 2: Detailed model of an individual prosumer in the energy community.

At each hour of the following day $t \in \mathcal{T}$, these loads may be supplied by heat and electricity exchanged with the grids or within the community, as well as by production from thermal generation, renewable energy, heat pumps, or storage units, as illustrated in [Figure 2](#). These represent

the space of decision variables of each prosumer in the community. Furthermore, a set of state variables, including the state of charge of heat and electricity storage units, the building's fabric temperatures, and upward and downward deviations from the indoor temperature comfort level at each hour of the following day $t \in \mathcal{T}$, represents the state of the prosumer and may influence its utility. This set of variables for all prosumers in the community $j \in \mathcal{N}$ and over all hours $t \in \mathcal{T}$ of the day is denoted by the matrix $X = [X_1, \dots, X_N] \in \mathbb{R}^{K_2 \times N}$, where each column $X_j \in \mathbb{R}^{K_2}$ represents the decision and state variables of a prosumer $j \in \mathcal{N}$ over all hours $t \in \mathcal{T}$ of the day.

Each prosumer $j \in \mathcal{N}$ holds private information that represents its load utilities and production costs, for all hours $t \in \mathcal{T}$ of the day, and the thermal characteristics of its building and the assets it owns. This set of true private preferences is denoted by $\tilde{\mathcal{B}}_j \in \mathbb{R}^{K_1}$. Prosumers are rational and self-interested, i.e., seeking to maximize their individual utilities, through their interactions with the rest of the community within the institutions of the proposed mechanism. For that, each prosumer submits bids to the community manager, denoted by the vector $\mathcal{B}_j \in \mathbb{R}^{K_1}$. The structure of the bids $\mathcal{B}_j \in \mathbb{R}^{K_1}$ impacts how the prosumers can represent and communicate their preferences. As outlined in Liu et al. (2015), adequate bid formats must represent the physical and economic characteristics of non-conventional flexibility assets, such as prosumers at the interface between heat and electricity systems. Therefore, in this community-based market mechanism, the economic characteristics of the prosumers are represented by a matrix $Q^c = [Q_1^c, \dots, Q_N^c] \in \mathbb{R}^{K_4 \times N}$, whose columns $Q_j^c \in \mathbb{R}^{K_4}$ represent the vectors of variable load utilities and production costs of a prosumer $j \in \mathcal{N}$ over all hours $t \in \mathcal{T}$ of the day. Additionally, the technical characteristics of the prosumers are represented by the set of matrices $Q^{(0)} \in \mathbb{R}^{K_3 \times N}$ and $Q^{(1)} \in \mathbb{R}^{K_2 \times N}$, whose columns $Q_j^{(0)} \in \mathbb{R}^{K_3}$ and $Q_j^{(1)} \in \mathbb{R}^{K_2}$ represent the vectors of technical parameters of a prosumer over all hours of the day. For notational simplicity, the dimensions K_3 , and K_4 represent the lengths of the vectors of preferences of the prosumers over all hours of the day, such that $K_1 = K_2 + K_3 + K_4$. These matrices can be derived from the compact and detailed expressions of the energy management problem, which will be introduced in Appendix B. Contrary to basic price-quantity bids, this generalized bid format allows the prosumers to model their cross-carrier flexibility and the synergies between different types of loads by a combination of linear constraints. These technical and economic parameters are detailed in Appendix B.

3.2. Energy management strategy of the community manager

The community manager chooses the optimal energy dispatch $X^{\mathcal{N}^*}(\mathcal{B})$ that maximizes the social welfare of the community with respect to the submitted bids \mathcal{B} . The linear objective function of the energy management problem is denoted by $\mathcal{H}(X, Q^c)$. This objective function is separable, with respect to each prosumer $j \in \mathcal{N}$. Additionally, we can differentiate the components $\mathcal{F}_j(X_j, Q_j^c)$ of the objective function which depend on the bids Q_j^c of the prosumers, representing the load utilities minus production costs, and the additional revenue $\mathcal{G}_j(X_j)$ from exchanges with the grids. The expression of these functions will be detailed in Appendix B. As a result, the social welfare of the community can be expressed as

$$\mathcal{H}(X, Q^c) = \sum_{j \in \mathcal{N}} \mathcal{H}_j(X_j, Q_j^c) = \sum_{j \in \mathcal{N}} (\mathcal{F}_j(X_j, Q_j^c) + \mathcal{G}_j(X_j)). \quad (3)$$

The community manager ensures that heat and electricity consumption and production are

balanced, by enforcing the following constraints

$$f^E \mathbf{1}_N = \mathbf{0}_T \quad (4a)$$

$$f^H \mathbf{1}_N = \mathbf{0}_T, \quad (4b)$$

where the matrices $f^E \in \mathbb{R}^{T \times N}$ and $f^H \in \mathbb{R}^{T \times N}$ represent the electricity and heat exchanges, respectively, within the community. The feasible space of any coalition of prosumers $\mathcal{S} \in 2^{\mathcal{N}}$ with respect to the submitted bids \mathcal{B} is represented by a set of linear equations

$$\Omega_{\mathcal{S}}(\mathcal{B}) = \left\{ X \in \mathbb{R}^{K_2 \times N} \mid (4a) - (4b), Q^{(2)} \left(X \circ Q^{(1)} \right) \leq Q^{(0)\mathcal{S}} \right\}, \quad (5)$$

where the operator \circ represents the Hadamard product, and the matrix $Q^{(2)} \in \mathbb{R}^{K_3 \times K_2}$ represents the shape of the operating constraints defined by the community manager. Additionally, the matrices $Q^{(0)} \in \mathbb{R}^{K_3 \times N}$ and $Q^{(1)} \in \mathbb{R}^{K_2 \times N}$ represent the bids of the prosumers. The matrix $Q^{(0)\mathcal{S}}$ is indexed by the coalition \mathcal{S} , which ensures that the column $Q_j^{(0)\mathcal{S}} = \mathbf{0}_{K_2}$ for any prosumer $j \notin \mathcal{S}$. Operations on matrices indexed by coalitions are defined in [Appendix A](#). In particular, $Q^{(0)\mathcal{S}} = [Q_1^{(0)} \delta_1^{\mathcal{S}}, \dots, Q_N^{(0)} \delta_N^{\mathcal{S}}]$, where the Dirac delta function is defined as

$$\delta^{\mathcal{S}} : k \in \mathcal{N} \mapsto \delta_k^{\mathcal{S}} = \begin{cases} 1 & \text{if } k \in \mathcal{S} \\ 0 & \text{otherwise} \end{cases}. \quad (6)$$

Note that, this feasible set is non-empty, because $\mathbf{0}_{K_2 \times T}$ is always feasible, and compact, because it includes upper and lower bounds on all the variables. A feasible solution with respect to the revealed preferences \mathcal{B} is denoted by $X^{\mathcal{S}}(\mathcal{B}) \in \Omega_{\mathcal{S}}(\mathcal{B})$. In particular, this definition of the feasible set of a coalition guarantees that a feasible solution $X_j^{\mathcal{S}}(\mathcal{B})$ for any prosumer $j \notin \mathcal{S}$ is fixed to zero.

The energy management problem of any coalition $\mathcal{S} \in 2^{\mathcal{N}}$ with respect to these revealed preferences \mathcal{B} can be expressed as the following linear program

$$\max_{X \in \Omega_{\mathcal{S}}(\mathcal{B})} \mathcal{H}(X, Q^c). \quad (7)$$

This optimization problem has a linear objective function and is defined on a convex, non-empty, and compact feasible set, hence it attains a global optimum $\theta^{\mathcal{S}}(\mathcal{B}) = \mathcal{H}(X^{\mathcal{S}*}(\mathcal{B}), Q^c)$ at an optimal solution

$$X^{\mathcal{S}*}(\mathcal{B}) \in \arg \max_{X \in \Omega_{\mathcal{S}}(\mathcal{B})} \mathcal{H}(X, Q^c). \quad (8)$$

Note that an optimal solution $X^{\mathcal{S}*}(\mathcal{B})$ of (7) and the optimal value $\theta^{\mathcal{S}}(\mathcal{B})$ are dependent on the bids of the prosumers in the coalition. In particular, the individual energy management problem is a special case of (7) for the coalition $\mathcal{S} = \{j\}$. The individual problem represents a *base-case* that we use for comparison purposes against the coalitional energy management problem. The detailed formulation of this mathematical problem is presented in [Appendix B](#).

As previously mentioned, in the proposed mechanism the value $v^{\mathcal{S}}(\mathcal{B})$ of a coalition $\mathcal{S} \in 2^{\mathcal{N}}$ is defined as the increase in social welfare between the individual problems of all prosumers $j \in \mathcal{S}$ and the coalitional problem, with respect to the revealed preferences \mathcal{B} , such that

$$v^{\mathcal{S}}(\mathcal{B}) = \theta^{\mathcal{S}}(\mathcal{B}) - \sum_{j \in \mathcal{S}} \theta^{\{j\}}(\mathcal{B}). \quad (9)$$

The *revealed utility* of a prosumer $j \in \mathcal{N}$ in this mechanism, which is defined as the utility with respect to its revealed preferences \mathcal{B}_j evaluated at the outcomes $X^{\mathcal{N}^*}(\mathcal{B})$, can be formulated as

$$u_j \left(X^{\mathcal{N}^*}(\mathcal{B}), \mathcal{B} \right) = \mathcal{P}_j \left(X^{\mathcal{N}^*}(\mathcal{B}) \right) + \mathcal{F}_j \left(X_j^{\mathcal{N}^*}(\mathcal{B}), Q_j^c \right) = \pi_j \left(X^{\mathcal{N}^*}(\mathcal{B}) \right) + \theta^{\{j\}}(\mathcal{B}), \quad \forall j \in \mathcal{N}. \quad (10)$$

By opposition, the *true utility* $u_j \left(X^{\mathcal{N}^*}(\mathcal{B}), \left(\tilde{\mathcal{B}}_j, \mathcal{B}_{-j} \right) \right)$ of a prosumer is defined as the utility with respect to its true preferences $\tilde{\mathcal{B}}_j$ evaluated at the outcomes $X^{\mathcal{N}^*}(\mathcal{B})$. This highlights the direct relationship between the payment rule of a mechanism and the allocation mechanism of the coalitional game form associated with this mechanism. As a result, the outcomes of the proposed mechanism with respect to the revealed preferences \mathcal{B} can equivalently be given by the pair of optimal dispatch and payment rule $(X^{\mathcal{N}^*}(\mathcal{B}), \mathcal{P}(X^{\mathcal{N}^*}(\mathcal{B})))$, or optimal dispatch and allocation mechanism $(X^{\mathcal{N}^*}(\mathcal{B}), \pi(X^{\mathcal{N}^*}(\mathcal{B})))$.

3.3. Payment rule and allocation mechanism

This section introduces different types of payment rules and allocation mechanisms that are commonly used in mechanism design. The properties of the proposed community-based market mechanism associated with these payments and allocation mechanisms will be studied in Section 4.

3.3.1. Uniform pricing

In the energy management problem (7), prosumers exchange heat and electricity within the community. Thus, by analogy with wholesale electricity markets, a common payment rule that can be used for exchanges within the community is based on uniform pricing. The revenues of each prosumer from exchanges within the community and with the grids are defined as

$$\begin{aligned} \mathcal{P}_j^\lambda \left(X_j^{\mathcal{N}^*}(\mathcal{B}), \lambda^{\mathcal{N}^*}(\mathcal{B}) \right) &= \left(\lambda^{E^{\mathcal{N}^*}}(\mathcal{B}) \right)^\top f_j^{E^{\mathcal{N}^*}}(\mathcal{B}) + \left(\lambda^{H^{\mathcal{N}^*}}(\mathcal{B}) \right)^\top f_j^{H^{\mathcal{N}^*}}(\mathcal{B}) \\ &+ \mathcal{G}_j \left(X_j^{\mathcal{N}^*}(\mathcal{B}) \right), \quad \forall j \in \mathcal{N}, \end{aligned} \quad (11)$$

where $f^{E^{\mathcal{N}^*}}(\mathcal{B})$ and $f^{H^{\mathcal{N}^*}}(\mathcal{B})$ represent the value of electricity and heat exchanges within the community, at an optimal solution $X^{\mathcal{N}^*}(\mathcal{B})$ of (7). Additionally, the uniform prices $\lambda^{E^{\mathcal{N}^*}}(\mathcal{B})$ and $\lambda^{H^{\mathcal{N}^*}}(\mathcal{B})$ represent the optimal value of the dual variables of (7) associated with the balance equations (4a) and (4b) at the optimal solution $X^{\mathcal{N}^*}(\mathcal{B})$. Note that the value of both the primal and dual variables at optimality are dependent on the submitted bids \mathcal{B} . For notational simplicity, we introduce the vector $\lambda^{\mathcal{N}^*}(\mathcal{B}) = [\lambda^{E^{\mathcal{N}^*}}(\mathcal{B}), \lambda^{H^{\mathcal{N}^*}}(\mathcal{B})] \in \mathbb{R}^{2T}$.

3.3.2. Vickrey-Clarke-Groves (VCG)

Another payment rule that has recently received increasing interest in the literature on electricity markets is the VCG payment rule with the Clarke pivot rule (Vickrey, 1961; Clarke, 1971; Groves, 1973; Green & Laffont, 1979). The revenue of each prosumer with this payment rule is defined as

$$\mathcal{P}_j^{\text{VCG}} \left(X^{\mathcal{N}^*}(\mathcal{B}) \right) = -\mathcal{F}_j \left(X_j^{\mathcal{N}^*}(\mathcal{B}), Q_j^c \right) + \left(\theta^{\mathcal{N} \setminus \{j\}}(\mathcal{B}) - \theta^{\mathcal{N}}(\mathcal{B}) \right), \quad j \in \mathcal{N}. \quad (12)$$

This payment rule represents the marginal contribution of each prosumer to the social welfare of the community. A series of recent studies has proposed VCG mechanisms applied to electricity markets Karaca et al. (2018); Karaca & Kamgarpour (2017); Sessa et al. (2017).

3.3.3. Shapley value

An allocation mechanism commonly used in cooperative game theory is the Shapley value, where each prosumer receives an allocation

$$\pi_j^s \left(X^{\mathcal{N}^*}(\mathcal{B}) \right) = \sum_{\mathcal{S} \in 2^{\mathcal{N}}} \frac{(|\mathcal{S}| - 1)! (N - |\mathcal{S}|)!}{N!} \left(v^{\mathcal{S}}(\mathcal{B}) - v^{\mathcal{S} \setminus \{j\}}(\mathcal{B}) \right) \delta_j^{\mathcal{S}}, \quad \forall j \in \mathcal{N}. \quad (13)$$

Note that the sum of the coefficients in the left-hand side of (13) is equal to one, i.e.

$$\sum_{\mathcal{S} \in 2^{\mathcal{N}}} \frac{(|\mathcal{S}| - 1)! (N - |\mathcal{S}|)!}{N!} \delta_j^{\mathcal{S}} = 1. \quad (14)$$

Therefore, this allocation mechanism associates to each prosumer $j \in \mathcal{N}$ its average marginal contribution to the values of all coalitions $\mathcal{S} \in 2^{\mathcal{N}}$. It is worth mentioning that the payment rule based on Shapley value requires computing the outcomes of the mechanism over all the coalitions in the community, which is computationally intensive.

3.3.4. Nucleolus

Finally, a well-known allocation mechanism in cooperative game theory is the nucleolus allocation $\pi^n \left(X^{\mathcal{N}^*}(\mathcal{B}) \right) \in \mathbb{R}^N$, which is defined as the allocation that minimizes the dissatisfaction of the prosumers with respect to the revealed information \mathcal{B} . In other words, the nucleolus is defined as the lexicographical maximum of the vector of excesses $\epsilon(\cdot)$ over all allocations, i.e.

$$\epsilon_{\mathcal{S}} \left(\pi^n \left(X^{\mathcal{N}^*}(\mathcal{B}) \right) \right) \leq \epsilon_{\mathcal{S}}(\tilde{\pi}(\mathcal{B})), \quad \forall \tilde{\pi}(\mathcal{B}) \in \mathcal{I}(v(\mathcal{B})), \quad \forall \mathcal{S} \in 2^{\mathcal{N}} \setminus \{\mathcal{N}, \emptyset\}. \quad (15)$$

The nucleolus allocation always exists and is unique (Schmeidler, 1969). However, its computation requires solving a sequence of $\mathcal{O}(2^N)$ linear programs, which is computationally intensive. In practice, we compute the nucleolus of the cooperative game $(\mathcal{N}, v(\mathcal{B}))$ defined in (9) by following steps (Guajardo & Jörnsten, 2015; Han et al., 2018):

1. We generate a complete list of the values $v^{\mathcal{S}}(\mathcal{B})$ by solving the energy management problem (7) for all coalitions $\mathcal{S} \in 2^{\mathcal{N}}$.
2. We solve the following linear problem (LP_1), which determines the maximum excess ϵ_1 among all potential coalitions:

$$\epsilon_1 = \min_{\epsilon, \pi \in \mathbb{R}^N} \epsilon \quad (16a)$$

$$\text{s.t.} \quad \sum_{j=1}^N \pi_j = v^{\mathcal{N}}(\mathcal{B}) \quad (16b)$$

$$\pi_j \geq 0, \quad \forall j \in \{1, \dots, N\} \quad (16c)$$

$$v^{\mathcal{S}}(\mathcal{B}) - \sum_{j \in \mathcal{S}} \pi_j \leq \epsilon, \quad \forall \mathcal{S} \in 2^{\mathcal{N}} \setminus \{\mathcal{N}, \emptyset\}, \quad (16d)$$

where (16b) enforces the efficient allocation property, and (16d) ensures that the excess of any coalition is lower than or equal to the maximum excess ϵ_1 . LP_1 gives us the set of coalitions Ψ_1 such that (16d) is binding. However, the nucleolus allocation has not yet been computed.

3. At any iteration $l > 1$, we solve a linear program (LP_l) which determines the maximum excess ϵ_l over all the coalitions that are not binding in the previous iterations $k < l$:

$$\epsilon_l = \min_{\epsilon, \pi \in \mathbb{R}^N} \epsilon \quad (17a)$$

$$\text{s.t.} \quad (16b) - (16c) \quad (17b)$$

$$v^{\mathcal{S}}(\mathcal{B}) - \sum_{j \in \mathcal{S}} \pi_j \leq \epsilon_k, \quad \forall \mathcal{S} \in \Psi_k, \forall k \in \{1, \dots, l-1\} \quad (17c)$$

$$v^{\mathcal{S}}(\mathcal{B}) - \sum_{j \in \mathcal{S}} \pi_j \leq \epsilon, \quad \forall \mathcal{S} \in 2^{\mathcal{N}} \setminus \{\mathcal{N}, \emptyset, \bigcup_{k=1}^{l-1} \Psi_k\}, \quad (17d)$$

where (17c) imposes that the excesses of all the coalitions $\mathcal{S} \in \Psi_k$ that are binding at iteration $k < l$ are lower than or equal to the maximum excess ϵ_k , which is defined as the optimal value of (LP_k) at iteration $k < l$. Additionally, (17d) enforces that all the excesses of the coalitions that are not binding in the previous iterations are lower than or equal to ϵ_l . LP_l gives us the set of coalitions Ψ_l such that (17d) is binding.

4. When a unique optimal solution is found, the solution $\pi^n(X^{\mathcal{N}^*}(\mathcal{B}))$ is the nucleolus allocation.

4. Properties of proposed community-based market mechanism and payment rules

This section analyzes the properties of the proposed community-based market mechanism along with different payment rules and allocation mechanisms. We first demonstrate the existence of core-selecting mechanisms for the proposed community-based market. In addition, we show that such a mechanism provides a trade-off between efficiency, incentive compatibility, and stability. We then discuss which specific payment rules and allocation mechanisms can achieve these desirable properties in the proposed community-based market mechanism. The proofs of these propositions are provided in [Appendix C](#). For the sake of self-containment, other well-known properties are also discussed.

4.1. Existence of core-selecting mechanisms

It results directly from the definition of the value function in (9) that $v^{\{i\}}(\mathcal{B}) = v^{\emptyset}(\mathcal{B}) = 0$, $\forall j \in \mathcal{N}$. In order to define the pair $(\mathcal{N}, v(\mathcal{B}))$ as a coalitional game form, the value function must be super-additive.

Proposition 1. *The value function $v^{\mathcal{S}}(\mathcal{B})$ defined in (9) is super-additive, and the pair $(\mathcal{N}, v(\mathcal{B}))$ defines a coalitional game form associated with the proposed community-based market mechanism.*

The proof of Proposition 1 is provided in [Appendix C](#). This property guarantees that the prosumers can benefit by forming the grand-coalition \mathcal{N} .

Despite this, it is common for practical cooperative games to have an empty core. The notion of *balanced game* is essential in cooperative game theory, as a cooperative game has a non-empty core if and only if it is balanced ([Scarf, 1967](#)).

Definition 6 (Balanced map). *A map $\alpha : 2^{\mathcal{N}} \rightarrow [0; 1]$ is balanced if $\sum_{\mathcal{S} \in 2^{\mathcal{N}}} \alpha(\mathcal{S}) \delta_j^{\mathcal{S}} = 1$, $\forall j \in \{1, \dots, N\}$.*

Definition 7 (Balanced game). *A cooperative game $(\mathcal{N}, v(\mathcal{B}))$ is balanced if for any balanced map α ,*

$$\sum_{S \in 2^{\mathcal{N}}} \alpha(S) v^S \leq v^{\mathcal{N}}. \quad (18)$$

An interesting property of the proposed community-based market mechanism is that, for any revealed preferences \mathcal{B} , the cooperative game defined by the pair $(\mathcal{N}, v(\mathcal{B}))$ is balanced, and thus has a non-empty revealed core.

Proposition 2. *For any preferences \mathcal{B} , the cooperative game defined by the pair $(\mathcal{N}, v(\mathcal{B}))$ is balanced.*

The proof of Proposition 2 is provided in Appendix C. As a result of this proposition, there exists a core-selecting mechanism $(X^{\mathcal{N}^*}(\mathcal{B}), \pi(X^{\mathcal{N}^*}(\mathcal{B})))$ that redistributes the value of the energy community among the agents in a fair way, with respect to the revealed preferences \mathcal{B} .

Furthermore, the outcomes $X^{\mathcal{N}^*}(\mathcal{B})$ of the energy management problem (7) maximize the social welfare of the community with respect to the revealed preferences \mathcal{B} . In order to guarantee that the true social welfare of the energy community is maximized, an allocation mechanism should provide incentives for agents to bid truthfully. Hence, the issue of modeling the behavior of the producers is central. We demonstrate an important linkage between the stability and incentive compatibility properties of the proposed cooperative game.

Proposition 3 (incentive optimality). *Any core-selecting mechanism $(X^{\mathcal{N}^*}(\mathcal{B}), \pi(X^{\mathcal{N}^*}(\mathcal{B})))$ of the cooperative game $(\mathcal{N}, v(\mathcal{B}))$ defined in (9) is Pareto efficient for the agents, and therefore, guarantees incentive optimality.*

This property ensures that a core-selecting mechanism for the cooperative game (9) selects an allocation that is Pareto efficient for the agents, and maximizes the incentives for the agents to bid truthfully (Day & Milgrom, 2008). This property arises from the structure of the energy procurement problem and the expression of the efficient allocation property in (1).

4.2. Properties of payment rules and allocation mechanisms

4.2.1. Stability

Among the proposed payment and allocation mechanisms, solely the nucleolus is known to be in the revealed core of any cooperative game when this set is non-empty, i.e., the game is balanced (Peters, 2015). Therefore, the proposed community-based market along with a nucleolus allocation mechanism defines a Core-selecting mechanism.

Although the Shapley value is, by construction, budget-balanced, there is no guarantee that it is in the revealed core of a cooperative game, even when this set is non-empty. In the case of the proposed community-based market mechanism, the case study in Section 5 shows that the Shapley value is not in the core of this game.

Furthermore, the VCG payment mechanism is not guaranteed to be budget-balanced or respect group rationality in the general case (Cavallo, 2006; Ausubel & Milgrom, 2006). Therefore, the community manager may incur financial losses, and prosumers are not guaranteed to be satisfied with the outcomes of the mechanism. In fact, Karaca et al. (2018) shows that the VCG mechanism is in the core of a game if and only if the objective value $\theta^{\mathcal{N}}(\mathcal{B})$ is submodular, i.e., has decreasing differences, which does not apply to the proposed community-based market mechanism. The

shortcomings of the VCG mechanism are explained in detail in [Ausubel & Milgrom \(2006\)](#); [Sessa et al. \(2017\)](#).

Finally, the uniform pricing payment mechanism is not in the revealed core of this cooperative game in the general case. Indeed, in the absence of network constraints or by redistributing congestion rents to transmission owners, the balance equations in (4a) and (4b) guarantee budget balance ([Schweppe et al., 1988](#)), but group rational is not guaranteed. Yet, we demonstrate in [Appendix C](#) that under the assumption of perfect competition this allocation mechanism is in the revealed core of the cooperative game.

Proposition 4. *Under the assumption of perfect competition, the community-based mechanism (7) with the payment rule \mathcal{P}^λ based on uniform pricing is a core-selecting mechanism.*

Note that the assumption of perfect competition is seldom verified in practice ([Wolfram, 1997](#); [Joskow & Kahn, 2001](#)), and may not be realistic for energy communities with a limited number of agents ([Hurwicz, 1972](#)).

4.2.2. Incentive compatibility

Among the proposed payment and allocation mechanisms, solely the VCG mechanism is known to be dominant-strategy incentive-compatible ([Hobbs et al., 2000](#); [Silva et al., 2001](#); [Zou et al., 2015](#); [Xu & Low, 2017](#); [Sessa et al., 2017](#); [Karaca & Kamgarpour, 2017](#); [Karaca et al., 2018](#)).

Proposition 3 guarantees that any core-selecting mechanism is incentive-optimal. This property limits the benefits that prosumers can derive by deviating from truthful bidding. In addition, it is practically hard for a prosumer to form a strategy that can impact the excess over all coalitions, which is the basis of the nucleolus mechanism. Hence, the nucleolus allocation mechanism is defined in such a way that makes it practically difficult for agents to deviate from a truth-telling strategy.

In the general case with a finite number of agents, the proposed mechanism with uniform pricing is not incentive compatible. It is known that in order to maintain efficiency and incentive compatibility, perfect competition must be assumed ([Wilson, 1977](#); [Hobbs et al., 2004](#); [Kazempour et al., 2018](#)). Otherwise, the outcomes of the mechanism $X^{\mathcal{N}^*}(\mathcal{B})$ and $\mathcal{P}^\lambda(X_j^{\mathcal{N}^*}(\mathcal{B}), \lambda^{\mathcal{N}^*}(\mathcal{B}))$ can be manipulated by the strategies \mathcal{B} of individual agents. Additionally, [Roberts & Postlewaite \(1976\)](#) shows that incentive compatibility is achievable in the limit, as the number of agents grows to infinity. In such an ideal condition, this payment rule converges towards the VCG mechanism.

4.2.3. Efficiency

As the nucleolus allocation defines a core-selecting mechanism, it is a coalition-proof mechanism ([Karaca et al., 2018](#)). Furthermore, the proposed community-based market mechanism with a VCG payment is known to be efficient (). However, this mechanism with uniform pricing may not be efficient. Indeed, although the community manager seeks to maximize the social welfare of the community, [Tang & Jain \(2013\)](#) shows that a Nash equilibrium may not exist in the general case. However, under the assumption of perfect competition, and therefore incentive compatibility, this mechanism is indeed efficient.

5. Illustrative case study: Impact and performance of the proposed mechanisms in a small community

In this section the concepts and properties previously introduced are illustrated through a case study. This illustrative example shows in practice the value that can be achieved by a group of pro-

sumers through cooperation, and briefly discusses how this value arises from the synergies between different types of loads. Furthermore, this case study highlights the impact of each payment rule and allocation mechanism on different types of prosumers, in terms of revenue and satisfaction. This case study setup and results are detailed in [Appendix D](#).

5.1. Individuals in the community

We consider an energy community with four prosumers, namely Christos, Anna, Vladimir and Andrea. These prosumers wish to design a community-based market mechanism to exchange their local energy production, and coordinate their energy procurement from the grid. The two main challenges to motivate these prosumers to join the community are to demonstrate the value of cooperating and redistribute fairly the value created.

In this community, each prosumer has a different type of energy usage and flexibility, as gathered in [Table 1](#). Christos owns an electric storage and rooftop solar panels, which production is assumed perfectly known, and at a zero marginal cost. Anna provides cross-carrier flexibility via a heat-pump, and owns a heat storage. Vladimir and Andrea have neither production units nor storage. However, Andrea has flexible indoor temperatures whereas Vladimir does not. In this case study, we model an asymmetric utility function for the deviations from the indoor temperature set-point, i.e., downward deviations are more penalized than upward deviations. Moreover, for simplicity, solely space heating loads and electricity consumption of heat pumps are assumed flexible. The electricity consumption of other electrical appliances and domestic hot water loads are considered inelastic and perfectly known for all prosumers.

Table 1: Flexible assets and loads of prosumers in the community.

	Christos	Anna	Vladimir	Andrea
Solar panel	Yes	No	No	No
Electricity storage	Yes	No	No	No
Heat storage	No	Yes	No	No
Heat pump	No	Yes	No	No
Electrical appliances	Inelastic	Inelastic	Inelastic	Inelastic
Domestic hot water	Inelastic	Inelastic	Inelastic	Inelastic
Space heating load	Elastic	Elastic	Inelastic	Elastic

These prosumers can exchange heat and electricity within the community, and with the grid. The import and export tariffs with the grid are modeled as hourly tariffs, of which the import price is systematically higher than the export price in order to account for grid tariffs. Heat and electricity export prices are proportional to the import prices, with a coefficient 0.9, in order to reflect the effect of grid tariffs on end-users.

For the sake of clarity and simplicity, we assume that the prosumers reveal their true preferences (though this is a dominant strategy under the VCG mechanism). Based on the true preferences of the prosumers, we solve the individual and community-based energy procurement problems for all hours of the following day. The results of this case study illustrate the impact of the community-based dispatch, and the different payment rules and allocation mechanisms on all four prosumers.

5.2. Value of cooperation

In this section, the impact of the community-based dispatch on the community as a whole and on individual prosumers is discussed. The community-based dispatch is compared to the

individual dispatch, in which each prosumer optimizes its energy procurement from the grids on its own. The difference in social welfare of the community between these two cases represents the value of cooperating as defined in (9). As reported in Table 2, the social welfare of the community is increased by 0.88€, i.e., 93%, compared to the individual case. This represents the value of cooperating for the community as a whole. This is achieved by exploiting the synergies between the prosumers and different types of loads. In particular, during the day, the community-based market mechanism is able to exploit the synergies between the cross-carrier flexibility offered by the heat pump belonging to Anna, and the excess electricity production from solar panels belonging to Christos. Additionally, during the night and evening, when electricity prices are low and heat demand is high, the community-based market mechanism is able to exploit the temperature flexibility of the prosumers, due to the heat pump belonging to Anna. These sources of flexibility and their synergies are under-utilized in the individual case.

Table 2: Absolute and relative difference in social welfare between the individual and community-based cases (in €, and %). The value of cooperation is calculated as the absolute difference in social welfare.

	Social welfare	Value of cooperation	Relative difference
Individual	-0.95€	-	-
Community-based	-0.07€	+0.88	+93%

5.3. Payment rules and allocation mechanisms

This section discusses the impact of the different allocation mechanisms on individual agents. Table 3 summarizes how the different allocation mechanisms redistribute the increase in social welfare among the four prosumers. As expected, the Shapley value, nucleolus, and uniform pricing mechanisms are efficient allocations, i.e., they are budget-balanced. However, the VCG mechanism incurs losses for the community manager, as the total allocation attributed to the prosumers exceeds the value of the community. This is a significant shortcoming for this mechanism, and an ex-post redistribution is required (Cavallo, 2006). Furthermore, the four allocation mechanisms considered are individually rational in this example, i.e., the allocations to all prosumers are positive. This guarantees that the prosumers are willingly participating in the proposed mechanisms.

Table 3: Value of the community, and allocation of this value attributed to each prosumer in the community (in €), with different allocation mechanisms.

	Christos	Anna	Vladimir	Andrea	Value of community
Uniform pricing	0.15	0.64	0.01	0.08	0.88
VCG	0.19	0.71	0.01	0.08	0.88
Shapley value	0.17	0.53	0.07	0.11	0.88
Nucleolus	0.11	0.69	0.01	0.07	0.88

Furthermore, the added value of each prosumer in the community can be analyzed through their marginal contributions to all coalitions. In this case study, Anna is the prosumer that has the highest marginal contribution to all coalitions. Christos has the second highest contribution, Andrea the third, and Vladimir the fourth. As the Shapley value is strongly-monotone, the allocations attributed to each agent monotonically follows their marginal contributions, as illustrated in Table 3.

In order to ensure fairness of the redistribution mechanism and satisfaction of all the prosumers, the allocation mechanisms should be in the core of the cooperative game. Table 4 summarizes the maximum excess over all coalitions, under the different allocation mechanisms. As expected, the nucleolus mechanism is stabilizing. In this example, the Shapley value is not in the core of the game because all coalitions that contain Anna have a positive excess. These coalitions have an incentive to split from the energy community to increase their social welfare. In order to ensure fairness of the redistribution and satisfaction of all the prosumers, the allocation mechanisms should be stabilizing, i.e., in the core of the cooperative game. Table 4 summarizes the maximum excess over all coalitions under the different allocation mechanisms. An allocation mechanism guarantees group rationality if and only if this maximum excess is non-positive. As expected, the nucleolus mechanism guarantees group rationality and is stabilizing. In this example, the Shapley value is not in the core of the cooperative game because all coalitions that contain Anna have a positive excess. Therefore, these coalitions have an incentive to split from the energy community to increase their social welfare. Furthermore, despite guaranteeing group rationality, the VCG mechanism is not in the core of the cooperative game because it is not an efficient allocation.

Table 4: Group rationality and stability of the different payment rules and allocation mechanisms.

		Uniform pricing	VCG	Shapley value	Nucleolus
Maximum excess	(EUR)	-0.001	-0.01	0.07	-0.007
Group rationality		Yes	Yes	No	Yes
Stability		Yes	No	No	Yes

6. Conclusion and future research directions

The community-based market mechanisms developed in this work provides a promising framework to coordinate the energy management of prosumers in local multi-carrier energy markets. This work highlights the value of harnessing the synergies between different types of loads and prosumers. The theoretical and applied contributions presented in this paper show that it is beneficial for the community as a whole to cooperate. However, it is known that no mechanism can satisfy stability, dominant-strategy incentive compatibility, and efficiency in the general case (Roth, 1982). Therefore, the four payment rules and allocation mechanisms studied only achieve certain of these fundamental mechanism properties. In particular, the nucleolus allocation is the only allocation that can guarantee stability in the general case. Furthermore, we demonstrate that it provides an interesting trade-off between stability, incentive-optimality, and efficiency. However, its main limitation is its computational complexity.

This work opens up various directions for future research, directed at consumer-centric market mechanism designers, as well as wholesale market operators and regulators. Firstly, uncertainty on the states of the system and exogenous perturbations should be accounted for in the optimal energy management of the community. Various studies have proposed robust control approaches for communities of buildings in multi-carrier energy systems via linear decision rules (Rey et al., 2018; Darivianakis et al., 2017a,b). Such approaches model the coordinated response of prosumers to exogenous deviations both from the grids, e.g. price signals or reserve activation, and outside conditions, e.g. renewable energy production of the community and temperatures. This approach would allow a better coordination between day-ahead scheduling and real-time operation of the flexible assets of the community, and reveal financial opportunities for this operational flexibility.

For that purpose, wholesale market mechanisms should evolve in order to integrate prosumers and other decentralized flexibility assets, such as micro CHPs, energy storage, across multiple energy systems. Novel trading mechanisms facilitating market access to these non-conventional sources of flexibility must be developed. In particular, a promising research direction consists of affine reserve policies, that model the coordinated response of flexible assets to deviations across multiple energy systems, time horizons and time scales (Warrington et al., 2013).

Furthermore, privacy concerns should be accounted for in the design of peer-to-peer and community-based market mechanisms. A widely used approach to preserve privacy is differential privacy, which protects sensitive information by adding systematic noise to the revealed preferences of the agents (Dwork et al., 2014; Dwork, 2008). An interesting extension to this work would be to investigate differentially-private consumer-centric market mechanisms. From a theoretical perspective, a number of recent studies in mechanism design have focused on the properties of differentially-private mechanisms. In addition to the intrinsic benefit of preserving private information, McSherry & Talwar (2007) shows that differentially private mechanisms can reduce the effect of the agents on the outcomes of the mechanism, and thus limit their incentives to misreport. Moreover, Forges & Minelli (2001) and Forges et al. (2001) study the relationship between incentive compatibility, stability, and efficiency of differentially private mechanisms. An alternative research direction to preserve privacy in decentralized optimization problem and mechanism designs, is to allow prosumers to communicate endogenous uncertainty sets of their preferences to the community. Building on the work by Darivianakis et al. (2018) and Zhang et al. (2017) the properties of a consumer-centric market mechanism with adjustable uncertainty sets should be investigated. From a technical perspective, the convergence and the trade-off between optimality and privacy of differentially-private decentralized optimization algorithms should be studied (Huang et al., 2015; Nozari et al., 2018; Bellet et al., 2017; Vanhaesebrouck et al., 2017). These algorithms, based on Lagrangian relaxation and the alternating direction of multipliers methods, may facilitate decentralized decision-making over peer-to-peer networks, while preserving privacy over sensitive information. However, they may fail to converge to a global optimal solution.

Finally, in order to fully exploit the potential of these decentralized flexibility assets, consumer-centric market mechanism designers, market operators and regulators need a better understanding of the motivations and behavior of prosumers and market participants. In particular, the field of behavioral economy and prospect theory (Kahneman & Tversky, 2013) provides a promising research direction by challenging the assumption of perfect rationality of agents in markets (Arthur, 1994; Sargent et al., 1993; Simon, 1997; Gigerenzer & Selten, 2002). In particular, such models have been applied to analyze the behavior of prosumers in energy markets (Stern, 1992; Sanstad & Howarth, 1994; Jaffe & Stavins, 1994; Wilson & Dowlatabadi, 2007; Gyamfi et al., 2013). Thus, integrating the notion of bounded rationality in community-based market mechanism design, and analyzing the properties of these mechanisms under this assumption would be an interesting extension of the work presented (Ming & Xie, 2014). Moreover, the effect of bounded rationality on wholesale markets and energy systems should be studied. Indeed, accounting for bounded rationality in the response of agents to demand response programs in energy policy and market design may help increase the cost-effectiveness of existing organizations (Allcott & Mullainathan, 2010).

Appendix A. Notations

This appendix summarizes the main notations and conventions used in this study.

Appendix A.1. Nomenclature

Sets and indexes

- \mathcal{T} Set of T time periods, typically the 24 hours of a day
- \mathcal{N} Grand-coalition of N prosumers
- $2^{\mathcal{N}}$ Set of all coalitions in the grand-coalition \mathcal{N}
- \mathcal{S}, \mathcal{V} Coalitions of prosumers in the grand-coalition \mathcal{N}
- $\tilde{\mathcal{B}}$ True preferences of the prosumers in the community, in $\mathbb{R}^{K_1 \times N}$
- \mathcal{B} Revealed preferences of prosumers in the community, in $\mathbb{R}^{K_1 \times N}$
- $\Omega_{\mathcal{S}}(\mathcal{B})$ Feasible region of the energy management problem of coalition \mathcal{S} , given the bids \mathcal{B} of prosumers

Parameters

- Q^c Matrix of revealed price preferences, in $\mathbb{R}^{K_4 \times N}$
- $Q^{(0)}$ Matrix of revealed technical parameters, in $\mathbb{R}^{K_3 \times N}$
- $Q^{(1)}$ Matrix of revealed technical parameters, in $\mathbb{R}^{K_2 \times N}$
- $Q^{(2)}$ Matrix representing the constraints of the energy management problem, in $\mathbb{R}^{K_3 \times K_2}$
- $c^{b,H}$ Vector of heat import prices, in \mathbb{R}^T (€/Wh)
- $c^{b,E}$ Vector of electricity import prices, in \mathbb{R}^T (€/Wh)
- $c^{s,H}$ Vector of heat export prices, in \mathbb{R}^T (€/Wh)
- $c^{s,E}$ Vector of electricity export prices, in \mathbb{R}^T (€/Wh)
- $c^{g,H}$ Matrix of heat production costs, in $\mathbb{R}^{T \times N}$ (€/Wh)
- $c^{g,E}$ Matrix of electricity production costs, in $\mathbb{R}^{T \times N}$ (€/Wh)
- c^E Matrix of elasticity parameters of electricity consumption, in $\mathbb{R}^{T \times N}$ (€/Wh)
- c^{HW} Matrix of elasticity parameters of hot water consumption, in $\mathbb{R}^{T \times N}$ (€/Wh)
- c^{up} Matrix of elasticity parameters of upward temperature deviations, in $\mathbb{R}^{T \times N}$ (€/°C)
- c^{down} Matrix of elasticity parameters of downward temperature deviations, in $\mathbb{R}^{T \times N}$ (€/°C)
- COP Matrix of coefficient of performance of heat pumps, in $\mathbb{R}^{T \times N}$
- T^{set} Matrix of set points of indoor temperatures, in $\mathbb{R}^{T \times N}$

- $en^{E,0}$ Matrix of initial charging state of electricity storage, in $\mathbb{R}^{T \times N}$ (Wh)
- $\rho^{ch,E}$ Matrix of charging efficiency coefficients of electricity storage, in $\mathbb{R}^{T \times N}$
- $\rho^{dis,E}$ Matrix of discharging efficiency coefficients of electricity storage, in $\mathbb{R}^{T \times N}$
- $en^{H,0}$ Matrix of initial charging state of heat storage, in $\mathbb{R}^{T \times N}$ (Wh)
- $\rho^{ch,H}$ Matrix of charging efficiency coefficients of heat storage, in $\mathbb{R}^{T \times N}$
- $\rho^{dis,H}$ Matrix of discharging efficiency coefficients of heat storage, in $\mathbb{R}^{T \times N}$
- ρ^E Matrix of electricity efficiency coefficients of thermal units, in $\mathbb{R}^{T \times N}$
- ρ^H Matrix of heat efficiency coefficients of thermal units, in $\mathbb{R}^{T \times N}$
- r Matrix of minimum heat to power ratios of thermal units, in $\mathbb{R}^{T \times N}$
- \bar{b}^E Matrix of upper bounds for electricity import from the grid, in $\mathbb{R}^{T \times N}$ (Wh)
- \bar{s}^E Matrix of upper bounds for electricity export to the grid, in $\mathbb{R}^{T \times N}$ (Wh)
- \bar{b}^H Matrix of upper bounds for heat import from the grid, in $\mathbb{R}^{T \times N}$ (Wh)
- \bar{s}^H Matrix of upper bounds for heat export to the grid, in $\mathbb{R}^{T \times N}$ (Wh)
- \bar{f}^E Matrix of upper bounds for electricity exchange within the community, in $\mathbb{R}^{T \times N}$ (Wh)
- \bar{f}^H Matrix of upper bounds for heat exchange within the community, in $\mathbb{R}^{T \times N}$ (Wh)
- $\bar{\Phi}^E$ Matrix of upper bounds for electricity production from thermal generation, in $\mathbb{R}^{T \times N}$ (Wh)
- $\bar{\Phi}^H$ Matrix of upper bounds for heat production from thermal generation, in $\mathbb{R}^{T \times N}$ (Wh)
- $\bar{\Phi}^{ENR}$ Matrix of upper bounds for electricity production from renewable energy, in $\mathbb{R}^{T \times N}$ (Wh)
- \bar{F} Matrix of upper bounds for fuel consumption from thermal generation, in $\mathbb{R}^{T \times N}$ (Wh)
- \bar{L}^{HP} Matrix of upper bounds for electricity consumption of heat-pump, in $\mathbb{R}^{T \times N}$ (Wh)
- \bar{en}^E Matrix of upper bounds for state of charge of electricity storage, in $\mathbb{R}^{T \times N}$ (Wh)
- \bar{en}^H Matrix of upper bounds for state of charge of heat storage, in $\mathbb{R}^{T \times N}$ (Wh)
- \bar{ch}^E Matrix of upper bounds for charging of electricity storage, in $\mathbb{R}^{T \times N}$ (Wh)
- \bar{ch}^H Matrix of upper bounds for charging of heat storage, in $\mathbb{R}^{T \times N}$
- \bar{dis}^E Matrix of upper bounds for discharging of electricity storage, in $\mathbb{R}^{T \times N}$ (Wh)
- \bar{dis}^H Matrix of upper bounds for discharging of heat storage, in $\mathbb{R}^{T \times N}$ (Wh)
- \bar{u}^{up} Matrix of upper bounds for upward indoor temperature deviations, in $\mathbb{R}^{T \times N}$ ($^{\circ}\text{C}$)

- \bar{u}^{down} Matrix of upper bounds for downward indoor temperature deviations, in $\mathbb{R}^{T \times N}$ ($^{\circ}\text{C}$)
- \bar{L}^{E} Matrix of upper bounds for bounds of electrical appliances consumption, in $\mathbb{R}^{T \times N}$ (Wh)
- \bar{L}^{HW} Matrix of upper bounds for hot water consumption, in $\mathbb{R}^{T \times N}$ (Wh)
- \bar{L}^{HP} Matrix of upper bounds for electric consumption of heat pump, in $\mathbb{R}^{T \times N}$ (Wh)
- \bar{L}^{SH} Matrix of upper bounds for space heating consumption, in $\mathbb{R}^{T \times N}$ (Wh)

Primal variables of energy management problem

- X Matrix of primal variables of the energy management problem, in $\mathbb{R}^{K_2 \times N}$
- b^{E} Matrix of electricity import, in $\mathbb{R}^{T \times N}$ (Wh)
- s^{E} Matrix of electricity export, in $\mathbb{R}^{T \times N}$ (Wh)
- b^{H} Matrix of heat import, in $\mathbb{R}^{T \times N}$ (Wh)
- s^{H} Matrix of heat export, in $\mathbb{R}^{T \times N}$ (Wh)
- f^{E} Matrix of electricity exchange within the community, in $\mathbb{R}^{T \times N}$ (Wh)
- f^{H} Matrix of heat exchange within the community, in $\mathbb{R}^{T \times N}$ (Wh)
- L^{E} Matrix of electrical appliances consumption, in $\mathbb{R}^{T \times N}$ (Wh)
- L^{HW} Matrix of hot water consumption, in $\mathbb{R}^{T \times N}$ (Wh)
- L^{HP} Matrix of electricity consumption for heat pump, in $\mathbb{R}^{T \times N}$ (Wh)
- L^{SH} Matrix of space heating consumption, in $\mathbb{R}^{T \times N}$ (Wh)
- T^{a} Matrix of indoor temperature, in $\mathbb{R}^{T \times N}$ ($^{\circ}\text{C}$)
- T^{s} Matrix of buildings' fabric temperature, in $\mathbb{R}^{T \times N}$ ($^{\circ}\text{C}$)
- u^{up} Matrix of upward deviations from indoor temperature set points, in $\mathbb{R}^{T \times N}$ ($^{\circ}\text{C}$)
- u^{down} Matrix of downward deviations from indoor temperature set points, in $\mathbb{R}^{T \times N}$ ($^{\circ}\text{C}$)
- Φ^{E} Matrix of electricity production from thermal generation, in $\mathbb{R}^{T \times N}$ (Wh)
- Φ^{H} Matrix of heat production from thermal generation, in $\mathbb{R}^{T \times N}$ (Wh)
- Φ^{ENR} Matrix of electricity production from renewables, in $\mathbb{R}^{T \times N}$ (Wh)
- ch^{E} Matrix of charging of electricity storage, in $\mathbb{R}^{T \times N}$ (Wh)
- dis^{E} Matrix of discharging of electricity storage, in $\mathbb{R}^{T \times N}$ (Wh)
- en^{E} Matrix of state of charge of electricity storage, in $\mathbb{R}^{T \times N}$ (Wh)

ch^H Matrix of charging of heat storage, in $\mathbb{R}^{T \times N}$ (Wh)

dis^H Matrix of discharging of heat storage, in $\mathbb{R}^{T \times N}$ (Wh)

en^H Matrix of state of charge of heat storage, in $\mathbb{R}^{T \times N}$ (Wh)

Functions

$\mathcal{H}(\cdot)$ Objective function of the energy management problem, representing the social welfare of the community (€)

$\mathcal{F}_j(\cdot)$ Utility of loads minus production cost of each prosumer $j \in \mathcal{N}$ (€)

$\mathcal{G}_j(\cdot)$ Revenue of each prosumer $j \in \mathcal{N}$ from exchanges with the grids (€)

$\mathcal{P}(\cdot)$ Vector of payment rules, whose entries $\mathcal{P}_j(\cdot)$ are the revenues of each prosumer $j \in \mathcal{N}$ (€)

$v(\cdot)$ Value function defined over the set of coalitions $2^{\mathcal{N}}$ (€)

$\pi(\cdot)$ Vector of allocations for a cooperative game (\mathcal{N}, v) , whose entries $\pi_j(\cdot)$ are the allocation of each prosumer $j \in \mathcal{N}$ (€)

$\epsilon(\cdot)$ Vector of excesses, whose entries $\epsilon_{\mathcal{S}}(\cdot)$ are the excess of each coalition $\mathcal{S} \in 2^{\mathcal{N}}$ (€)

$u(\cdot)$ Vector of utilities, whose entries $u_j(\cdot)$ are the individual utilities of each prosumer $j \in \mathcal{N}$ (€)

The dual variables of the energy management problem are not detailed in this nomenclature. However, they will be introduced in [Appendix B](#), along with the constraints that they are associated with.

Appendix A.2. Conventions

In this paper we use the following conventions and mathematical operators. For any matrix $A = [A_1, \dots, A_J] \in \mathbb{R}_{I \times J}$, we denote the column $A_j \in \mathbb{R}^I$ for any $j \in \{1, \dots, J\}$. We define $A^T \in \mathbb{R}_{J \times I}$ the transpose matrix, such that $A_{j,i}^T = A_{i,j}$, $\forall i \in \{1, \dots, I\}, \forall j \in \{1, \dots, J\}$. We define $A_j \in \mathbb{R}_I$ the vector of the j^{th} column, and $(A)_i^T \in \mathbb{R}_J$ the vector of the i^{th} line. The operators $\leq, \geq, =$, and \perp , are used element-by-element. For instance, for $A \in \mathbb{R}_{I \times J}$ and $B \in \mathbb{R}_{I \times J}$, the inequality $A \leq B$ is understood as $A_{i,j} \leq B_{i,j}$, $\forall i \in \{1, \dots, I\}, \forall j \in \{1, \dots, J\}$.

The Euclidean inner product between $A \in \mathbb{R}_{I \times K}$ and $B \in \mathbb{R}_{K \times J}$, is defined as $(AB)_{i,j} = \sum_{k=1}^K A_{i,k} B_{k,j}$, for $i \in \{1, \dots, I\}$ and $j \in \{1, \dots, J\}$. In particular, the right-side product of matrix $A \in \mathbb{R}_{I \times T}$ with the column vector of ones $\mathbf{1}_T$ represents a sum over the rows of the matrix $A \in \mathbb{R}_{I \times T}$, and the left-side product with the row vector of ones $\mathbf{1}_{1 \times I}$ represents a sum of the columns of the matrix $A \in \mathbb{R}_{I \times T}$.

We denote \circ as the Hadamard product between two matrices of the same dimensions $A, B \in \mathbb{R}_{I \times J}$, such that $A \circ B = (A_{i,j} B_{i,j})_{1 \leq i \leq I, 1 \leq j \leq J}$. By extension we define the Hadamard product between a matrix $A \in \mathbb{R}_{I \times J}$ and a column vector $\vec{B} \in \mathbb{R}_I$ as $A \circ \vec{B} = [A_1 \circ \vec{B}, \dots, A_J \circ \vec{B}] \in \mathbb{R}_{I \times J}$.

Furthermore, a matrix $Z = [Z_1, \dots, Z_N] \in \mathbb{R}^{M \times N}$, with the columns $Z_j \in \mathbb{R}^M$ for $j \in \{1, \dots, N\}$, indexed by a coalition $\mathcal{S} \in 2^{\mathcal{N}}$ is defined as $Z^{\mathcal{S}} = [Z_1 \delta_1^{\mathcal{S}}, \dots, Z_N \delta_N^{\mathcal{S}}]$. Following this definition, we introduce the summation operation of the coalition superscripts.

Definition 8 (Coalition summation). For a matrix $Z = [Z_1, \dots, Z_N] \in \mathbb{R}^{M \times N}$, and the coalitions $\mathcal{S}_k \in 2^N$, and $a_k \geq 0$ for $j \in \{1, \dots, 2^N\}$ is defined as:

$$Z^{\sum_{k=1}^{2^N} a_k \mathcal{S}_k} = \left[\sum_{k=1}^{2^N} a_k Z_1 \delta_1^{\mathcal{S}_k}, \dots, \sum_{k=1}^{2^N} a_k Z_N \delta_N^{\mathcal{S}_k} \right]. \quad (\text{A.1})$$

From (A.1), we can derive the following:

$$Z^{\sum_{k=1}^{2^N} a_k \mathcal{S}_k} = \sum_{k=1}^{2^N} \left[a_k Z_1 \delta_1^{\mathcal{S}_k}, \dots, a_k Z_N \delta_N^{\mathcal{S}_k} \right] = \sum_{k=1}^{2^N} Z^{a_k \mathcal{S}_k} = \sum_{k=1}^{2^N} a_k Z^{\mathcal{S}_k}. \quad (\text{A.2})$$

In particular, for $\mathcal{S} \in 2^N, \mathcal{V} \in 2^N$ such that $\mathcal{S} \cap \mathcal{V} = \emptyset$, we have $\delta_j^{\mathcal{S}} + \delta_j^{\mathcal{V}} = \delta_j^{\mathcal{S} \cup \mathcal{V}}, \forall j \in \{1, \dots, N\}$. Hence, $Z^{\mathcal{S}} + Z^{\mathcal{V}} = Z^{\mathcal{S} \cup \mathcal{V}}$.

Appendix B. Mathematical formulations

This Appendix details the mathematical models representing the dynamics and constraints of the prosumers, and the energy management problem of the community manager.

Appendix B.1. Temperature dynamics of buildings

We introduce the following additional notations representing the technical characteristics of the buildings in the community:

C_j^a Thermal capacity of the indoor air of a building $j \in \mathcal{N}$ (J/°C)

C_j^s Thermal inertia of the fabric of a building $j \in \mathcal{N}$ (J/°C)

$T_{t,j}^e$ External outdoor air temperatures of a building $j \in \mathcal{N}$ at time $t \in \mathcal{T}$ (°C)

T_j^g Ground temperature of a building $j \in \mathcal{N}$ (°C)

$T_{t,j}^v$ Ventilation supply air temperature of a building $j \in \mathcal{N}$ at time $t \in \mathcal{T}$ (°C)

H_j^{ae} Sum of the infiltration heat capacity flow and windows heat conductance (W/°C)

H_j^{as} Sum of heat conductance in the solid wall and convection on the surface (W/°C)

H_j^{ag} Floor heat conductance (W/°C)

H_j^{av} Ventilation air heat capacity flow (W/°C)

H_j^{se} Sum of heat conductance in the solid wall and convection on the surface (W/°C)

$\Phi_{t,j}^R$ Total heating power from solar radiation, and internal heat gains of a building $j \in \mathcal{N}$ at time $t \in \mathcal{T}$ (W)

Note that every parameter depends on the building type except for $T_{t,j}^e$ and T_j^g , which depend on the location of the building. The parameter $\Phi_{t,j}^R$ depends on the location and the building type.

Based on the set of differential equations introduced in (Alahäivälä et al., 2017) representing the temporal dynamics of the ambient room temperatures $T^a \in \mathbb{R}^{T \times N}$, the building's fabric temperatures $T^s \in \mathbb{R}^{T \times N}$, we can derive the following linear model:

$$\alpha_j^3 T_{t,j}^a - T_{t-1,j}^a = \alpha_{t,j}^0 + \alpha_j^1 T_{t,j}^s + \alpha_j^2 L_{t,j}^{\text{SH}}, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.1a})$$

$$\beta_j^2 T_{t,j}^s - T_{t-1,j}^s = \beta_{t,j}^0 + \beta_j^1 T_{t,j}^a, \quad \forall j \in \mathcal{N}, t \in \mathcal{T}, \quad (\text{B.1b})$$

where the parameters are defined as

$$\alpha_{t,j}^0 = \frac{\Delta t}{C_j^a} \left(H_j^{\text{ae}} T_{t,j}^e + H_j^{\text{ag}} T_j^g + H_j^{\text{av}} T_{t,j}^v + \Phi_{t,j}^R \right), \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.2a})$$

$$\alpha_j^1 = \frac{\Delta t}{C_j^a} H_j^{\text{as}}, \quad \forall j \in \mathcal{N} \quad (\text{B.2b})$$

$$\alpha_j^2 = \frac{\Delta t}{C_j^a}, \quad \forall j \in \mathcal{N} \quad (\text{B.2c})$$

$$\alpha_j^3 = 1 + \frac{\Delta t}{C_j^a} \left(H_j^{\text{ae}} + H_j^{\text{as}} + H_j^{\text{ag}} + H_j^{\text{av}} \right) \quad (\text{B.2d})$$

$$\beta_{t,j}^0 = \frac{\Delta t}{C_j^s} H_j^{\text{se}} T_{t,j}^e, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.2e})$$

$$\beta_j^1 = \frac{\Delta t}{C_j^s} H_j^{\text{as}}, \quad \forall j \in \mathcal{N} \quad (\text{B.2f})$$

$$\beta_j^2 = 1 + \frac{\Delta t}{C_j^s} \left(H_j^{\text{as}} + H_j^{\text{se}} \right), \quad \forall j \in \mathcal{N}, \quad (\text{B.2g})$$

where Δt represents the discretization of the time steps (in seconds). Equations (B.1) can be reformulated in a compact form as

$$T^a = A^0 + \sum_{k=1}^T M^{(k)} T^s \circ A^{1,k} + \sum_{k=1}^T M^{(k)} L^{\text{SH}} \circ A^{2,k} \quad (\text{B.3a})$$

$$T^s = B^0 + \sum_{k=1}^T M^{(k)} T^a \circ B^{1,k}, \quad (\text{B.3b})$$

where the matrices $A^0 \in \mathbb{R}^{T \times N}$, $A^{1,k} \in \mathbb{R}^{T \times N}$, $A^{2,k} \in \mathbb{R}^{T \times N}$, $B^0 \in \mathbb{R}^{T \times N}$, and $B^{1,k} \in \mathbb{R}^{T \times N}$ are

defined by

$$A_{t,j}^0 = \sum_{\tau=1}^T \frac{\alpha_{\tau,j}^0}{\left(\alpha_j^3\right)^{t+1-\tau}} + \frac{1}{\left(\alpha_j^3\right)^T} T_j^{a,0}, \quad \forall j \in \mathcal{N}, \forall t \in \mathcal{T} \quad (\text{B.4a})$$

$$A_{t,j}^{1,k} = \frac{\alpha_j^1}{\left(\alpha_j^3\right)^k}, \quad \forall j \in \mathcal{N}, \forall k \in \mathcal{T}, \forall t \in \mathcal{T} \quad (\text{B.4b})$$

$$A_{t,j}^{2,k} = \frac{\alpha_j^2}{\left(\alpha_j^3\right)^k}, \quad \forall j \in \mathcal{N}, \forall t \in \mathcal{T} \quad (\text{B.4c})$$

$$B_{t,j}^0 = \sum_{\tau=1}^T \frac{\beta_{\tau,j}^0}{\left(\beta_j^2\right)^{t+1-\tau}} + \frac{1}{\left(\beta_j^2\right)^T} T_j^{s,0}, \quad \forall j \in \mathcal{N}, \forall t \in \mathcal{T} \quad (\text{B.4d})$$

$$B_{t,j}^{1,k} = \frac{\beta_j^1}{\left(\beta_j^2\right)^k}, \quad \forall j \in \mathcal{N}, \forall k \in \mathcal{T}, \forall t \in \mathcal{T}, \quad (\text{B.4e})$$

and, for any $k \in \{1, \dots, T\}$ the lower-triangular matrix $M^{(k)} \in \mathbb{R}_{T \times T}$ is defined as

$$M_{i,j}^{(k)} = \begin{cases} 1 & \text{if } i = j - 1 + k \\ 0 & \text{otherwise,} \end{cases}$$

such that $M^{(k)} = \mathbb{I}_{T \times T}$ is the identity matrix, and $\sum_{k=1}^T M^{(k)} = \mathbf{1}_{T \times T}^\downarrow$ is the lower triangular matrix which lower coefficients are all equal to 1. The left-side product of a matrix with the matrix $M^{(k)}$ represents the selection of the elements of that matrix at time $T - k$.

Appendix B.2. Energy management problem: extended formulation

In this section we introduce an extended formulation of the energy management problem of the community manager introduced in Section 3.

Appendix B.2.1. Decision variables

For each prosumer $j \in \mathcal{N}$, we distinguish three main types of variable loads over all hours $t \in \mathcal{T}$ of the day, depending on the utility that is derived from them, rather than the energy carrier (district heating or electricity) consumed:

1. **Space heating:** $L_j^{\text{SH}} \in \mathbb{R}^T$ is the energy needed at each hour to heat a building. This load can be supplied by district heating, or electricity (via heat pumps). In order to model the flexibility of space heating loads, the temperature dynamics of each building are represented through a set of linear equations detailed in Appendix B (Alahäivälä et al., 2017). The utility derived from space heating is defined with respect to a vector of temperature comfort level $T_j^{\text{set}} \in \mathbb{R}^T$, and vectors of upward and downward deviation range $\bar{u}_j^{\text{up}} \in \mathbb{R}_+^T$, $\bar{u}_j^{\text{down}} \in \mathbb{R}_+^T$.
2. **Domestic hot water:** $L_j^{\text{HW}} \in \mathbb{R}^T$ is the energy needed at each hour in the form of domestic hot water. This load can be supplied either by district heating, assuming that the district heating supply temperature is sufficient, or by electricity (via heat pumps).
3. **Heat pumps:** $L_j^{\text{HP}} \in \mathbb{R}^T$ designates the electricity consumption of heat pumps.

4. **Electrical appliances:** $L_j^E \in \mathbb{R}^T$ designates all electrical loads that do not serve the purpose of supplying one of the two aforementioned loads, i.e., heat pumps are not included.

The space of decisions for each prosumer $j \in \mathcal{N}$ over all hours of the following day, includes their import and export of heat and electricity from the grids $b_j^H \in \mathbb{R}_+^T$, $b_j^E \in \mathbb{R}_+^T$, $s_j^H \in \mathbb{R}_+^T$, $s_j^E \in \mathbb{R}_+^T$, the exchange of heat and electricity within the community $f_j^H \in \mathbb{R}^T$, $f_j^E \in \mathbb{R}^T$, flexible loads, electricity production from renewable energy $\Phi_j^{\text{ENR}} \in \mathbb{R}^T$, heat and electricity production from thermal units $\Phi_j^H \in \mathbb{R}_+^T$, $\Phi_j^E \in \mathbb{R}_+^T$, charging and discharging of the heat and electricity storage units $ch_j^E \in \mathbb{R}_+^T$, $dis_j^E \in \mathbb{R}_+^T$, $ch_j^H \in \mathbb{R}_+^T$, $dis_j^H \in \mathbb{R}_+^T$. For notational simplicity, we assume that each prosumer has at most one of each type of generation or storage units. Furthermore, a set of state variables defined over all hours $t \in \mathcal{T}$ of the day, including the state of charge of heat and electricity storage units $en_j^E \in \mathbb{R}_+^T$, $en_j^H \in \mathbb{R}_+^T$, the indoor and fabric temperatures of the building $T_j^a \in \mathbb{R}_+^T$, $T_j^s \in \mathbb{R}_+^T$, upward and downward deviations from the temperature comfort level $u_j^{\text{up}} \in \mathbb{R}_+^T$, $u_j^{\text{down}} \in \mathbb{R}_+^T$, represents the state of the prosumer and may influence its utility. This set of variables for all prosumers in the community and over all hours of the planning horizon is denoted by the matrix $X = [X_1, \dots, X_N] \in \mathbb{R}^{K_2 \times N}$, where each column

$$X_j = [b_j^H, b_j^E, s_j^H, s_j^E, f_j^H, f_j^E, \Phi_j^H, \Phi_j^E, L_j^{\text{SH}}, L_j^{\text{HW}}, L_j^E, u_j^{\text{up}}, u_j^{\text{down}}, T_j^s, T_j^a, en_j^E, en_j^H, ch_j^E, dis_j^E, en_j^H, ch_j^H, dis_j^H] \in \mathbb{R}^{K_2} \quad (\text{B.5})$$

represents the decision variables of a prosumer $j \in \mathcal{N}$ over all hours of the following day.

Appendix B.2.2. Community manager problem

The energy management problem of a coalition $\mathcal{S} \in 2^N$ solved by the community manager with respect to the revealed preferences \mathcal{B} can be formulated as

$$\max \left[\mathbf{1}_{1 \times T} (L^E \circ c^E + L^{HW} \circ c^{HW} - u^{\text{up}} \circ c^{\text{up}} - u^{\text{down}} \circ c^{\text{down}} - \Phi^H \circ c^{\text{g,H}} - \Phi^E \circ c^{\text{g,E}}) + c^{\text{s,E}^\top} s^E + c^{\text{s,H}^\top} s^H - c^{\text{b,E}^\top} b^E - c^{\text{b,H}^\top} b^H \right] \mathbf{1}_N \quad (\text{B.6a})$$

$$\text{s.t. (4a) - (4b): } \lambda^E, \lambda^H \quad (\text{B.6b})$$

$$\Phi^{\text{ENR}} + \Phi^E - L^E - L^{\text{HP}} + \text{dis}^E - \text{ch}^E = f^E + s^E - b^E : \gamma^E \quad (\text{B.6c})$$

$$\Phi^H + L^{\text{HP}} \circ \text{COP} - L^{\text{SH}} - L^{\text{HW}} + \text{dis}^H - \text{ch}^H = f^H + s^H - b^H : \gamma^H \quad (\text{B.6d})$$

$$T^{\text{a}} = A^{0^{\text{S}}} + \sum_{k=1}^T M^{(k)} (T^{\text{s}} \circ A^{1,k}) + \sum_{k=1}^T M^{(k)} (L^{\text{SH}} \circ A^{2,k}) : \gamma^{T^{\text{a}}} \quad (\text{B.6e})$$

$$T^{\text{a}} = T^{\text{set}^{\text{S}}} + u^{\text{up}} - u^{\text{down}} : \gamma^{T^{\text{set}}} \quad (\text{B.6f})$$

$$T^{\text{s}} = B^{0^{\text{S}}} + \sum_{k=1}^T M^{(k)} (T^{\text{a}} \circ B^{1,k}) : \gamma^{T^{\text{s}}} \quad (\text{B.6g})$$

$$\text{en}^E = \text{en}^{E,0^{\text{S}}} + \mathbf{1}_{T \times T}^\downarrow (ch^E \circ \rho^{\text{ch,E}} - \text{dis}^E \circ \rho^{\text{dis,E}}) : \gamma^{\text{en}^E} \quad (\text{B.6h})$$

$$\text{en}^H = \text{en}^{H,0^{\text{S}}} + \mathbf{1}_{T \times T}^\downarrow (ch^H \circ \rho_j^{\text{ch,H}} - \text{dis}^H \circ \rho^{\text{dis,H}}) : \gamma^{\text{en}^H} \quad (\text{B.6i})$$

$$\text{en}_T^E \geq \text{en}_T^{E,0^{\text{S}}} : \mu^{\text{en,E}^0} \quad (\text{B.6j})$$

$$\text{en}_T^H \geq \text{en}_T^{H,0^{\text{S}}} : \mu^{\text{en,H}^0} \quad (\text{B.6k})$$

$$\Phi^E \circ \rho^E + \Phi_j^H \circ \rho^H \leq \bar{F}^{\text{S}} : \bar{\mu}^F \quad (\text{B.6l})$$

$$\Phi_j^H \circ r \leq \Phi^E : \mu^r \quad (\text{B.6m})$$

$$\mathbf{0}_{T \times N} \leq b^E \leq \bar{b}^{E^{\text{S}}}, \mathbf{0}_{T \times N} \leq s^E \leq \bar{s}^{E^{\text{S}}} : \underline{\mu}^{b^E}, \bar{\mu}^{b^E}, \underline{\mu}^{s^E}, \bar{\mu}^{s^E} \quad (\text{B.6n})$$

$$\mathbf{0}_{T \times N} \leq b^H \leq \bar{b}^{H^{\text{S}}}, \mathbf{0}_{T \times N} \leq s^H \leq \bar{s}^{H^{\text{S}}} : \underline{\mu}^{b^H}, \bar{\mu}^{b^H}, \underline{\mu}^{s^H}, \bar{\mu}^{s^H} \quad (\text{B.6o})$$

$$-\bar{f}^{E^{\text{S}}} \leq f^E \leq \bar{f}^{E^{\text{S}}}, -\bar{f}^{H^{\text{S}}} \leq f^H \leq \bar{f}^{H^{\text{S}}} : \underline{\mu}^{f^E}, \bar{\mu}^{f^E}, \underline{\mu}^{f^H}, \bar{\mu}^{f^H} \quad (\text{B.6p})$$

$$\mathbf{0}_{T \times N} \leq \Phi^E \leq \bar{\Phi}^{E^{\text{S}}}, \mathbf{0}_{T \times N} \leq \Phi^H \leq \bar{\Phi}^{H^{\text{S}}} : \underline{\mu}^{\Phi^E}, \bar{\mu}^{\Phi^E}, \underline{\mu}^{\Phi^H}, \bar{\mu}^{\Phi^H} \quad (\text{B.6q})$$

$$\mathbf{0}_{T \times N} \leq \Phi^{\text{ENR}} \leq \bar{\Phi}^{\text{ENR}^{\text{S}}} : \underline{\mu}^{\Phi^{\text{ENR}}}, \bar{\mu}^{\Phi^{\text{ENR}}} \quad (\text{B.6r})$$

$$\mathbf{0}_{T \times N} \leq u^{\text{up}} \leq \bar{u}^{\text{up}^{\text{S}}}, \mathbf{0}_{T \times N} \leq u^{\text{down}} \leq \bar{u}^{\text{down}^{\text{S}}} : \underline{\mu}^{u^{\text{up}}}, \bar{\mu}^{u^{\text{up}}}, \underline{\mu}^{u^{\text{down}}}, \bar{\mu}^{u^{\text{down}}} \quad (\text{B.6s})$$

$$\mathbf{0}_{T \times N} \leq L^E \leq \bar{L}^{E^{\text{S}}}, \mathbf{0}_{T \times N} \leq L^{\text{HP}} \leq \bar{L}^{\text{HP}^{\text{S}}} : \underline{\mu}^{L^E}, \bar{\mu}^{L^E}, \underline{\mu}^{L^{\text{HP}}}, \bar{\mu}^{L^{\text{HP}}} \quad (\text{B.6t})$$

$$\mathbf{0}_{T \times N} \leq L^{\text{HW}} \leq \bar{L}^{\text{HW}^{\text{S}}}, \mathbf{0}_{T \times N} \leq L^{\text{SH}} \leq \bar{L}^{\text{SH}^{\text{S}}} : \underline{\mu}^{L^{\text{HW}}}, \bar{\mu}^{L^{\text{HW}}}, \underline{\mu}^{L^{\text{SH}}}, \bar{\mu}^{L^{\text{SH}}} \quad (\text{B.6u})$$

$$\mathbf{0}_{T \times N} \leq \text{en}^E \leq \bar{\text{en}}^{E^{\text{S}}}, \mathbf{0}_{T \times N} \leq \text{en}^H \leq \bar{\text{en}}^{H^{\text{S}}} : \underline{\mu}^{\text{en}^E}, \bar{\mu}^{\text{en}^E}, \underline{\mu}^{\text{en}^H}, \bar{\mu}^{\text{en}^H} \quad (\text{B.6v})$$

$$\mathbf{0}_{T \times N} \leq \text{ch}^E \leq \bar{\text{ch}}^{E^{\text{S}}}, \mathbf{0}_{T \times N} \leq \text{ch}^H \leq \bar{\text{ch}}^{H^{\text{S}}} : \underline{\mu}^{\text{ch}^E}, \bar{\mu}^{\text{ch}^E}, \underline{\mu}^{\text{ch}^H}, \bar{\mu}^{\text{ch}^H} \quad (\text{B.6w})$$

$$\mathbf{0}_{T \times N} \leq \text{dis}^E \leq \bar{\text{dis}}^{E^{\text{S}}}, \mathbf{0}_{T \times N} \leq \text{dis}^H \leq \bar{\text{dis}}^{H^{\text{S}}} : \underline{\mu}^{\text{dis}^E}, \bar{\mu}^{\text{dis}^E}, \underline{\mu}^{\text{dis}^H}, \bar{\mu}^{\text{dis}^H}. \quad (\text{B.6x})$$

The dual variables are denoted in front of the constraints they are associated with. Equation (B.6b) represents the heat and electricity balance for the community, and the associated dual variables represent the heat and electricity uniform prices introduced in Section 3. Equations (B.6c) and (B.6d) represent the heat and electricity balance of individual prosumers in the community, (B.6e)-(B.6g) model the temperature dynamics of the buildings, (B.6h)-(B.6k) model the dynamics and state of charge of the heat and electricity storage units, and (B.6n)-(B.6x) represent the upper bounds for all the decision variables. Furthermore, (B.6l) and (B.6m) represent a general formulation of the linking constraints between the heat and electricity outputs of thermal units, which encompass extraction CHPs, heat-only, and thermal power plants. In particular, (B.6l) represents the maximum fuel consumption, as a function of heat and electricity outputs, and (B.6m) represents the minimum heat to power ratio of thermal units.

This linear optimization problem may be reformulated in the compact form (7) by introducing the matrix $Q^c = [Q_1^c, \dots, Q_N^c] \in \mathbb{R}^{K_4 \times N}$, which columns represent the load utilities and production costs of the prosumers over all hours $t \in \mathcal{T}$ of the day, i.e.

$$Q_j^c = \left[c_j^E, c_j^{\text{HW}}, c_j^{\text{up}}, c_j^{\text{down}}, c_j^{\text{g,E}}, c_j^{\text{g,H}} \right] \in \mathbb{R}^{K_4}, \quad \forall j \in \mathcal{N}, \quad (\text{B.7})$$

and the matrices $Q^{(0)} \in \mathbb{R}^{K_3 \times N}$, $Q^{(1)} \in \mathbb{R}^{K_2 \times N}$, $Q^{(2)} \in \mathbb{R}^{K_3 \times K_2}$ which represent the feasible region of the decision variables $X \in \mathbb{R}^{K_2 \times N}$ over all hours $t \in \mathcal{T}$ of the day. These matrices of technical parameters can be directly derived from the expression of the constraints (B.6c)-(B.6x).

Furthermore, the objective function (B.6a) can be separated for each prosumer $j \in \mathcal{N}$ into the element that depend on their bids Q_j^c , i.e.

$$\begin{aligned} \mathcal{F}_j(X_j, Q_j^c) = \mathbf{1}_{1 \times T} \left(L_j^E \circ c_j^E + L_j^{\text{HW}} \circ c_j^{\text{HW}} - u_j^{\text{up}} \circ c_j^{\text{up}} - u_j^{\text{down}} \circ c_j^{\text{down}} \right. \\ \left. - \Phi_j^{\text{H}} \circ c_j^{\text{g,H}} - \Phi_j^{\text{E}} \circ c_j^{\text{g,E}} \right), \quad \forall j \in \mathcal{N}, \end{aligned} \quad (\text{B.8})$$

and the additional revenue from exchanges with the grid, i.e.

$$\mathcal{G}_j(X_j) = c_j^{\text{s,E}^\top} s_j^{\text{E}} + c_j^{\text{s,H}^\top} s_j^{\text{H}} - c_j^{\text{b,E}^\top} b_j^{\text{E}} - c_j^{\text{b,H}^\top} b_j^{\text{H}}, \quad \forall j \in \mathcal{N}. \quad (\text{B.9})$$

Appendix B.3. Energy management problem: Karush-Kuhn-Tucker (KKT) conditions

In the following we provide a detailed expression of the KKT conditions of the energy management problem (B.6). This formulation will be used to demonstrate the equivalence between this optimization problem and an equilibrium problem, where each (price-taker) agent tries to maximize its own profit in the community.

As the energy management problem (B.6) is linear in the continuous variables $X \in \mathbb{R}^{K_2 \times N}$, it

is equivalent to its KKT conditions, which can be expressed as

$$\frac{\partial \mathcal{L}}{\partial f_{t,j}^E} = -\lambda_{t,j}^E + \gamma_{t,j}^E - \underline{\mu}_{t,j}^{f^E} + \bar{\mu}_{t,j}^{f^E} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10a})$$

$$\frac{\partial \mathcal{L}}{\partial f_{t,j}^H} = -\lambda_{t,j}^H + \gamma_{t,j}^H - \underline{\mu}_{t,j}^{f^H} + \bar{\mu}_{t,j}^{f^H} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10b})$$

$$\frac{\partial \mathcal{L}}{\partial b_{t,j}^E} = c_t^{b,E} - \gamma_{t,j}^E - \underline{\mu}_{t,j}^{b^E} + \bar{\mu}_{t,j}^{b^E} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10c})$$

$$\frac{\partial \mathcal{L}}{\partial b_{t,j}^H} = c_t^{b,H} - \gamma_{t,j}^H - \underline{\mu}_{t,j}^{b^H} + \bar{\mu}_{t,j}^{b^H} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10d})$$

$$\frac{\partial \mathcal{L}}{\partial s_{t,j}^E} = -c_t^{s,E} + \gamma_{t,j}^E - \underline{\mu}_{t,j}^{s^E} + \bar{\mu}_{t,j}^{s^E} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10e})$$

$$\frac{\partial \mathcal{L}}{\partial s_{t,j}^H} = -c_t^{s,H} + \gamma_{t,j}^H - \underline{\mu}_{t,j}^{s^H} + \bar{\mu}_{t,j}^{s^H} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10f})$$

$$\frac{\partial \mathcal{L}}{\partial \Phi_{t,j}^E} = c_j^{g,E} - \gamma_{t,j}^E - \underline{\mu}_{t,j}^{\Phi^E} + \bar{\mu}_{t,j}^{\Phi^E} + \bar{\mu}_{t,j}^F \rho_{t,j}^E - \mu_{t,j}^r = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10g})$$

$$\frac{\partial \mathcal{L}}{\partial \Phi_{t,j}^H} = c_j^{g,H} - \gamma_{t,j}^H - \underline{\mu}_{t,j}^{\Phi^H} + \bar{\mu}_{t,j}^{\Phi^H} + \bar{\mu}_{t,j}^F \rho_{t,j}^H + \mu_{t,j}^r r_{t,j} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10h})$$

$$\frac{\partial \mathcal{L}}{\partial \Phi_{t,j}^{\text{ENR}}} = -\gamma_{t,j}^E - \underline{\mu}_{t,j}^{\Phi^{\text{ENR}}} + \bar{\mu}_{t,j}^{\Phi^{\text{ENR}}} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10i})$$

$$\frac{\partial \mathcal{L}}{\partial L_{t,j}^E} = -c_{t,j}^E + \gamma_{t,j}^E - \underline{\mu}_{t,j}^{L^E} + \bar{\mu}_{t,j}^{L^E} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10j})$$

$$\frac{\partial \mathcal{L}}{\partial L_{t,j}^{\text{HP}}} = \gamma_{t,j}^E - \text{COP}_{t,j} \gamma_{t,j}^H + \bar{\mu}_{t,j}^{L^{\text{HP}}} - \underline{\mu}_{t,j}^{L^{\text{HP}}} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10k})$$

$$\frac{\partial \mathcal{L}}{\partial L_{t,j}^{\text{HW}}} = -c_{t,j}^{\text{HW}} + \gamma_{t,j}^H - \underline{\mu}_{t,j}^{L^{\text{HW}}} + \bar{\mu}_{t,j}^{L^{\text{HW}}} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10l})$$

$$\frac{\partial \mathcal{L}}{\partial L_{t,j}^{\text{SH}}} = \gamma_{t,j}^H + \sum_{k,\tau=1}^T M_{\tau,t}^{(k)} A_{t,j}^{2,k} \gamma_{\tau,j}^{T^a} - \underline{\mu}_{t,j}^{L^{\text{SH}}} + \bar{\mu}_{t,j}^{L^{\text{SH}}} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10m})$$

$$\frac{\partial \mathcal{L}}{\partial \text{en}_{t,j}^E} = -\gamma_{t,j}^{\text{en}^E} - \underline{\mu}_{t,j}^{\text{en}^E} + \bar{\mu}_{t,j}^{\text{en}^E} - \mu^{\text{en},E^0} \delta_t^T = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10n})$$

$$\frac{\partial \mathcal{L}}{\partial \text{en}_{t,j}^H} = -\gamma_{t,j}^{\text{en}^H} - \underline{\mu}_{t,j}^{\text{en}^H} + \bar{\mu}_{t,j}^{\text{en}^H} - \mu^{\text{en},H^0} \delta_t^T = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10o})$$

$$\frac{\partial \mathcal{L}}{\partial \text{ch}_{t,j}^E} = \gamma_{t,j}^E + \sum_{\tau=1}^T \mathbf{1}_{\tau,t}^\downarrow \rho_{t,j}^{\text{ch}^E} \gamma_{\tau,j}^{\text{en}^E} - \underline{\mu}_{t,j}^{\text{ch}^E} + \bar{\mu}_{t,j}^{\text{ch}^E} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10p})$$

$$\frac{\partial \mathcal{L}}{\partial \text{ch}_{t,j}^H} = \gamma_{t,j}^H + \sum_{\tau=1}^T \mathbf{1}_{\tau,t}^\downarrow \rho_{t,j}^{\text{ch}^H} \gamma_{\tau,j}^{\text{en}^H} - \underline{\mu}_{t,j}^{\text{ch}^H} + \bar{\mu}_{t,j}^{\text{ch}^H} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10q})$$

$$\frac{\partial \mathcal{L}}{\partial \text{dis}_{t,j}^E} = -\gamma_{t,j}^E - \sum_{\tau=1}^T \mathbf{1}_{\tau,t}^\downarrow \rho_{t,j}^{\text{dis}^E} \gamma_{\tau,j}^{\text{en}^E} - \underline{\mu}_{t,j}^{\text{dis}^E} + \bar{\mu}_{t,j}^{\text{dis}^E} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10r})$$

$$\frac{\partial \mathcal{L}}{\partial \text{dis}_{t,j}^H} = -\gamma_{t,j}^H - \sum_{\tau=1}^T \mathbf{1}_{\tau,t}^\downarrow \rho_{t,j}^{\text{dis}^H} \gamma_{\tau,j}^{\text{en}^H} - \underline{\mu}_{t,j}^{\text{dis}^H} + \bar{\mu}_{t,j}^{\text{dis}^H} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10s})$$

$$\frac{\partial \mathcal{L}}{\partial T_{t,j}^a} = -\gamma_{t,j}^{T^{\text{set}}} - \gamma_{t,j}^{T^a} + \sum_{k,\tau=1}^T M_{\tau,t}^{(k)} B_{t,j}^{1,k} \gamma_{\tau,j}^{T^s} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10t})$$

$$\frac{\partial \mathcal{L}}{\partial T_{t,j}^s} = -\gamma_{t,j}^{T^s} + \sum_{k,\tau=1}^T M_{\tau,t}^{(k)} A_{t,j}^{1,k} \gamma_{\tau,j}^{T^a} - \underline{\mu}_{j,t}^{T^s} + \bar{\mu}_{j,t}^{T^s} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10u})$$

$$\frac{\partial \mathcal{L}}{\partial u_{t,j}^{\text{up}}} = +c_{t,j}^{\text{up}} + \gamma_{t,j}^{T^{\text{set}}} - \underline{\mu}_{j,t}^{u^{\text{up}}} + \bar{\mu}_{j,t}^{u^{\text{up}}} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10v})$$

$$\frac{\partial \mathcal{L}}{\partial u_{t,j}^{\text{down}}} = +c_{t,j}^{\text{down}} - \gamma_{t,j}^{T^{\text{set}}} - \underline{\mu}_{j,t}^{u^{\text{down}}} + \bar{\mu}_{j,t}^{u^{\text{down}}} = 0, \quad \forall j \in \mathcal{N}, t \in \mathcal{T} \quad (\text{B.10w})$$

$$\mathbf{0}_{T \times N} \leq \bar{\mu}^F \perp \left(\bar{F}^S - \Phi^E \circ \rho^E - \Phi^H \circ \rho^H \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10x})$$

$$\mathbf{0}_{T \times N} \leq \mu^r \perp \left(\Phi^E - \Phi^H \circ r \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10y})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{b^E} \perp b^E \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{b^E} \perp \left(\bar{b}^{E^S} - b^E \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10z})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{s^E} \perp s^E \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{s^E} \perp \left(\bar{s}^{E^S} - s^E \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10aa})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{b^H} \perp b^H \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{b^H} \perp \left(\bar{b}^{H^S} - b^H \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10ab})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{s^H} \perp s^H \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{s^H} \perp \left(\bar{s}^{H^S} - s^H \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10ac})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{f^E} \perp \left(\bar{f}^{E^S} + f^E \right) \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{f^E} \perp \left(\bar{f}^{E^S} - f^E \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10ad})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{f^H} \perp \left(\bar{f}^{H^S} + f^H \right) \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{f^H} \perp \left(\bar{f}^{H^S} - f^H \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10ae})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{\Phi^E} \perp \Phi^E \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{\Phi^E} \perp \left(\bar{\Phi}^{E^S} - \Phi^E \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10af})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{\Phi^H} \perp \Phi^H \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{\Phi^H} \perp \left(\bar{\Phi}^{H^S} - \Phi^H \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10ag})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{\Phi^{\text{ENR}}} \perp \Phi^{\text{ENR}} \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{\Phi^{\text{ENR}}} \perp \left(\bar{\Phi}^{\text{ENR}^S} - \Phi^{\text{ENR}} \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10ah})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{u^{\text{up}}} \perp u^{\text{up}} \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{u^{\text{up}}} \perp \left(\bar{u}^{\text{up}^S} - u^{\text{up}} \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10ai})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{u^{\text{down}}} \perp u^{\text{down}} \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{u^{\text{down}}} \perp \left(\bar{u}^{\text{down}^S} - u^{\text{down}} \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10aj})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{L^E} \perp L^E \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{L^E} \perp \left(\bar{L}^{E^S} - L^E \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10ak})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{L^{\text{HP}}} \perp L^{\text{HP}} \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{L^{\text{HP}}} \perp \left(\bar{L}^{\text{HP}^S} - L^{\text{HP}} \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10al})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{L^{\text{HW}}} \perp L^{\text{HP}} \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{L^{\text{HW}}} \perp \left(\bar{L}^{\text{HW}^S} - L^{\text{HW}} \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10am})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{L^{\text{SH}}} \perp L^{\text{SH}} \geq 0, \mathbf{0}_{T \times N} \leq \bar{\mu}^{L^{\text{SH}}} \perp \left(\bar{L}^{\text{SH}^S} - L^{\text{SH}} \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10an})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{en^E} \perp en^E \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{en^E} \perp \left(\bar{en}^{E^S} - en^E \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10ao})$$

$$\mathbf{0}_T \leq \mu^{en, E^0} \perp \left((en_T^E)^\top - (en_T^{E, 0^S})^\top \right) \geq \mathbf{0}_T \quad (\text{B.10ap})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{en^H} \perp en^H \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{en^H} \perp \left(\bar{en}^{H^S} - en^H \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10aq})$$

$$\mathbf{0}_T \leq \mu^{en, H^0} \perp \left((en_T^H)^\top - (en_T^{H, 0^S})^\top \right) \geq \mathbf{0}_T \quad (\text{B.10ar})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{ch^E} \perp ch^E \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{ch^E} \perp \left(\bar{ch}^{E^S} - ch^E \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10as})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{ch^H} \perp ch^H \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{ch^H} \perp \left(\bar{ch}^{H^S} - ch^H \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10at})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{dis^E} \perp dis^E \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{dis^E} \perp \left(\bar{dis}^{E^S} - dis^E \right) \geq \mathbf{0}_{T \times N} \quad (\text{B.10au})$$

$$\mathbf{0}_{T \times N} \leq \underline{\mu}^{dis^H} \perp dis^H \geq \mathbf{0}_{T \times N}, \mathbf{0}_{T \times N} \leq \bar{\mu}^{dis^H} \perp \left(\bar{dis}^{H^S} - dis^H \right) \geq \mathbf{0}_{T \times N}. \quad (\text{B.10av})$$

Appendix C. Proofs

This Appendix presents the proofs of the properties introduced in this work.

Appendix C.1. Proof of Proposition 1: super-additivity of value function

In order to prove Proposition 1, we first formulate the following lemma:

Lemma 1. *The optimal objective function of the energy management problem $\theta(\cdot)$ is super-additive, i.e., for any preferences $\mathcal{B} \in \mathbb{R}^{K_1 \times N}$, set of coalitions $\mathcal{S} \in 2^N$, and $\mathcal{V} \in 2^N$, and positive real values $a \geq 0$ and $b \geq 0$,*

$$\theta^{a\mathcal{S}+b\mathcal{V}}(\mathcal{B}) \geq \theta^{a\mathcal{S}}(\mathcal{B}) + \theta^{b\mathcal{V}}(\mathcal{B}). \quad (\text{C.1})$$

Appendix C.1.1. Proof of Lemma 1

For any feasible solutions $X \in \Omega_{\mathcal{S}}(\mathcal{B})$ and $Y \in \Omega_{\mathcal{V}}(\mathcal{B})$, from the formulation of the constraints (B.6b)-(B.6x), it is straightforward that the matrix $aX + bY$ is in the feasible space $\Omega_{(a\mathcal{S}+b\mathcal{V})}(\mathcal{B})$. In particular, for $X^{\mathcal{S}^*}(\mathcal{B}) \in \Omega_{\mathcal{S}}(\mathcal{B})$ and $X^{\mathcal{V}^*}(\mathcal{B}) \in \Omega_{\mathcal{V}}(\mathcal{B})$, we can derive that the optimal solution of the energy management problem over the coalition $(a\mathcal{S} + b\mathcal{V})$ satisfies

$$\theta^{(a\mathcal{S}+b\mathcal{V})}(\mathcal{B}) = \mathcal{H}\left(X^{(a\mathcal{S}+b\mathcal{V})^*}(\mathcal{B}), Q^c\right) \geq \mathcal{H}\left(aX^{\mathcal{S}^*}(\mathcal{B}) + bX^{\mathcal{V}^*}(\mathcal{B}), Q^c\right). \quad (\text{C.2})$$

As the objective function $\mathcal{H}(X, Q^c)$ in (B.6a) is a linear map, it results

$$\theta^{(a\mathcal{S}+b\mathcal{V})}(\mathcal{B}) \geq a\mathcal{H}\left(X^{\mathcal{S}^*}(\mathcal{B}), Q^c\right) + b\mathcal{H}\left(X^{\mathcal{V}^*}(\mathcal{B}), Q^c\right) = a\theta^{\mathcal{S}}(\mathcal{B}) + b\theta^{\mathcal{V}}(\mathcal{B}). \quad (\text{C.3})$$

Appendix C.1.2. Proof of Proposition 1

Let us consider $\mathcal{B} \in \mathbb{R}^{K_1 \times N}$, $\mathcal{S} \in 2^{\mathcal{N}}$, $\mathcal{V} \in 2^{\mathcal{N}}$, such that $\mathcal{S} \cap \mathcal{V} = \emptyset$, and $a \geq 0$, $b \geq 0$, and let us prove that $v^{\mathcal{S} \cup \mathcal{V}}(\mathcal{B}) \geq v^{\mathcal{S}}(\mathcal{B}) + v^{\mathcal{V}}(\mathcal{B})$. It results from the summation operation on coalition superscripts in the special case where $\mathcal{S} \cap \mathcal{V} = \emptyset$ that $\Omega_{\mathcal{S}+\mathcal{V}}(\mathcal{B}) = \Omega_{\mathcal{S} \cup \mathcal{V}}(\mathcal{B})$, and $\theta^{\mathcal{S}+\mathcal{V}}(\mathcal{B}) = \theta^{\mathcal{S} \cup \mathcal{V}}(\mathcal{B})$. Thus,

$$v^{\mathcal{S} \cup \mathcal{V}}(\mathcal{B}) = \theta^{\mathcal{S} \cup \mathcal{V}}(\mathcal{B}) - \sum_{j \in \mathcal{S} \cup \mathcal{V}} \theta^{\{j\}}(\mathcal{B}) = \theta^{(\mathcal{S}+\mathcal{V})}(\mathcal{B}) - \sum_{j \in \mathcal{S}} \theta^{\{j\}}(\mathcal{B}) - \sum_{j \in \mathcal{V}} \theta^{\{j\}}(\mathcal{B}). \quad (\text{C.4})$$

It follows from the super-additivity of the optimal objective value demonstrated in Lemma 1 that

$$v^{\mathcal{S} \cup \mathcal{V}}(\mathcal{B}) \geq \theta^{\mathcal{S}}(\mathcal{B}) - \theta^{\mathcal{V}}(\mathcal{B}) - \sum_{j \in \mathcal{S}} \theta^{\{j\}}(\mathcal{B}) - \sum_{j \in \mathcal{V}} \theta^{\{j\}}(\mathcal{B}) = v^{\mathcal{S}}(\mathcal{B}) + v^{\mathcal{V}}(\mathcal{B}). \quad (\text{C.5})$$

Appendix C.2. Proof of Proposition 2: balancedness of cooperative game

Let us consider a balanced map α , as introduced in Definition 7, and the preferences $\mathcal{B} \in \mathbb{R}^{K_1 \times N}$, and let us prove that the value function $v(\mathcal{B})$ defined in (9) is balanced. By definition, the value function can be formulated as

$$\begin{aligned} \sum_{\mathcal{S} \in 2^{\mathcal{N}}} \alpha(\mathcal{S}) v^{\mathcal{S}}(\mathcal{B}) &= \sum_{\mathcal{S} \in 2^{\mathcal{N}}} \alpha(\mathcal{S}) \left[\theta^{\mathcal{S}}(\mathcal{B}) - \sum_{j \in \mathcal{S}} \theta^{\{j\}}(\mathcal{B}) \right] \\ &= \sum_{\mathcal{S} \in 2^{\mathcal{N}}} \alpha(\mathcal{S}) \theta^{\mathcal{S}}(\mathcal{B}) - \sum_{j \in \mathcal{N}} \left(\sum_{\mathcal{S} \in 2^{\mathcal{N}}} \alpha(\mathcal{S}) \delta_j^{\mathcal{S}} \right) \theta^{\{j\}}(\mathcal{B}) \\ &= \sum_{\mathcal{S} \in 2^{\mathcal{N}}} \alpha(\mathcal{S}) \theta^{\mathcal{S}}(\mathcal{B}) - \sum_{j \in \mathcal{N}} \theta^{\{j\}}(\mathcal{B}). \end{aligned} \quad (\text{C.6})$$

Furthermore, Lemma 1, with the positive values $\alpha(\mathcal{S}) \geq 0$, guarantees that

$$\sum_{\mathcal{S} \in 2^{\mathcal{N}}} \alpha(\mathcal{S}) \theta^{\mathcal{S}}(\mathcal{B}) \leq \theta^{\sum_{\mathcal{S} \in 2^{\mathcal{N}}} \alpha(\mathcal{S}) \mathcal{S}}(\mathcal{B}). \quad (\text{C.7})$$

And, by definition of the coalition summation in (A.1), the optimal value indexed by coalition superscripts can be reformulated as

$$\begin{aligned} \theta^{\sum_{\mathcal{S} \in 2^{\mathcal{N}}} \alpha(\mathcal{S}) \mathcal{S}}(\mathcal{B}) &= \theta^{\sum_{\mathcal{S} \in 2^{\mathcal{N}}} \alpha(\mathcal{S}) \sum_{j \in \mathcal{S}} \{j\}}(\mathcal{B}) = \theta^{\sum_{j \in \mathcal{N}} (\sum_{\mathcal{S} \in 2^{\mathcal{N}}} \alpha(\mathcal{S}) \delta_j^{\mathcal{S}}) \{j\}}(\mathcal{B}) = \theta^{\sum_{j \in \mathcal{N}} \{j\}}(\mathcal{B}) \\ &= \theta^{\mathcal{N}}(\mathcal{B}). \end{aligned} \quad (\text{C.8})$$

By replacing (C.7) and (C.8) in the right-hand side of (C.6), we get

$$\sum_{\mathcal{S} \in 2^{\mathcal{N}}} \alpha(\mathcal{S}) v^{\mathcal{S}} \leq \theta^{\mathcal{N}}(\mathcal{B}) - \sum_{j \in \mathcal{N}} \theta^{\{j\}}(\mathcal{B}) = v^{\mathcal{N}} \theta^{\mathcal{N}}(\mathcal{B}). \quad (\text{C.9})$$

This inequality shows that the cooperative game considered in this work is balanced, and has a non-empty core.

Appendix C.3. Proof of Proposition 3: bidder-optimality of core-selecting mechanisms

Let us consider a core-selecting mechanism that, for the submitted bids \mathcal{B} , selects the outcomes $X^{\mathcal{N}^*}(\mathcal{B}), \pi(X^{\mathcal{N}^*}(\mathcal{B}))$ of the energy management problem (7), such that the allocation mechanism is in the revealed core $\mathcal{C}(\mathcal{N}, v^{\mathcal{N}}(\mathcal{B}))$. Let us show that this allocation mechanism is Pareto efficient for the agents. This property directly ensues from the efficient allocation property of the revealed core.

We assume that there exists one other allocation in the revealed core $\hat{\pi}(\mathcal{B}) \in \mathcal{C}(\mathcal{N}, v^{\mathcal{N}}(\mathcal{B}))$ that dominates $\pi(X^{\mathcal{N}^*}(\mathcal{B}))$, i.e., such that $\hat{\pi}_j(\mathcal{B}) \geq \pi_j(X^{\mathcal{N}^*}(\mathcal{B}))$, $\forall j \in \mathcal{N}$ and the inequality is strict for at least one prosumer $j \in \mathcal{N}$. As a result, the efficient allocation property ensures that

$$v^{\mathcal{N}}(\mathcal{B}) = \sum_{j \in \mathcal{N}} \hat{\pi}_j(\mathcal{B}) > \sum_{j \in \mathcal{N}} \pi_j(X^{\mathcal{N}^*}(\mathcal{B})) = v^{\mathcal{N}}(\mathcal{B}). \quad (\text{C.10})$$

As $v^{\mathcal{N}}(\mathcal{B})$ is defined as the global minimum of a convex function over a convex and compact set, the strict inequality (C.10) is impossible. This shows that there exists no such allocation $\hat{\pi}(\mathcal{B})$ in the revealed core that dominates $\pi(X^{\mathcal{N}^*}(\mathcal{B}))$. This shows that, by design, all core-selecting mechanisms for the cooperative game defined in (9) are bidder efficient and thus incentive-optimal.

Appendix C.4. Proof of Proposition 4: group rationality of uniform pricing

In the proposed community-based market mechanism, we demonstrate that the uniform pricing payment rule is a core-selecting mechanism under the assumption of perfect competition.

Appendix C.4.1. Non-cooperative equilibrium under perfect competition assumption

Under the assumption of perfect competition, the uniform prices payment rule has been shown to be dominant-strategy incentive compatible and efficient³. Hence, truthful bidding, i.e., $\mathcal{B} = \tilde{\mathcal{B}}$, is a dominant strategy for all agents $j \in \mathcal{N}$. Additionally, all optimal solutions of the energy procurement problem (7) coincide with and efficient Nash equilibriums of the utility maximization problems of the individual agents.

The non-cooperative equilibrium problem, where the prosumers in a coalition $j \in \mathcal{S} \in 2^{\mathcal{N}}$ try to maximize their individual utilities $u_j(X_j(\mathcal{B}), \lambda(\mathcal{B}, \mathcal{B}_j))$, is denoted by $Eq.^{\mathcal{S}}$. Under perfect competition assumption, the utility maximization problem of an individual agent in the grand coalition $j \in \mathcal{N}$ in this equilibrium problem $Eq.^{\mathcal{S}}$ can be formulated as follows:

$$\max_{X_j \in \mathcal{K}_j^{\mathcal{S}}(\mathcal{B}_j)} u_j(X_j, \lambda, \mathcal{B}_j), \quad (\text{C.11})$$

where the feasible space is defined as

$$\mathcal{K}_j^{\mathcal{S}} = \left\{ X_j \in \mathbb{R}_{K_2} \mid Q_j^{(2)}(X_j \circ Q_j^{(1)}) \leq Q_j^{0^{\mathcal{S}}} \right\}. \quad (\text{C.12})$$

Note that the expression of the feasible space $\mathcal{K}_j^{\mathcal{S}}(\mathcal{B}_j)$ of each prosumer $j \in \mathcal{N}$, indexed by the coalition \mathcal{S} , ensures that any feasible decision variable $X_j^{\mathcal{S}} \in \mathcal{K}_j^{\mathcal{S}}(\mathcal{B}_j)$ is fixed to zero if $j \notin \mathcal{S}$. In addition, the linking constraints (4a) and (4b) are added to this equilibrium problem to ensure

³The proofs of these properties rely on the strong duality and complementarity theorems of the energy management problem.

balance of heat and electricity exchanges within the coalition $\mathcal{S} \in 2^{\mathcal{N}}$. The uniform prices $\lambda^E \in \mathbb{R}^T$ and $\lambda^H \in \mathbb{R}^T$ are derived as dual variables of these balance equations at equilibrium.

The objective of the utility maximization problem (C.11) of each prosumer depends on the uniform prices $\lambda = [\lambda^E, \lambda^H] \in \mathbb{R}^{2T}$. Under the assumption of perfect competition, each prosumer models these prices are independent from its decisions, i.e., as fixed parameters in (C.11). It results from this assumption, that the KKT conditions of the equilibrium problem $Eq.^{\mathcal{S}}$ are identical to the KKT conditions of the energy management problem (7) for a coalition $\mathcal{S} \in 2^{\mathcal{N}}$, which are detailed in Appendix B.3. As these KKT conditions are necessary and sufficient, any optimal solution to the energy management problem (7) for a coalition $\mathcal{S} \in 2^{\mathcal{N}}$ coincides with an efficient Nash equilibrium of the equilibrium problem $Eq.^{\mathcal{S}}$, and vice versa.

Appendix C.4.2. Efficient allocation

It has been shown that the uniform pricing payment rule \mathcal{P}^λ is budget-balanced for any revealed preferences $\mathcal{B} \in \mathbb{R}^{K_1 \times N}$. In other words, it defines an efficient allocation mechanism π^λ , such that $\pi_j^\lambda \left(X_j^{\mathcal{N}^*}(\mathcal{B}), \lambda^{\mathcal{N}^*}(\mathcal{B}) \right) = \mathcal{P}_j^\lambda \left(X_j^{\mathcal{N}^*}(\mathcal{B}), \lambda^{\mathcal{N}^*}(\mathcal{B}) \right) + \mathcal{F}_j \left(X_j^{\mathcal{N}^*}(\mathcal{B}), Q_j^c \right) - \theta^{\{j\}}(\mathcal{B})$, $\forall j \in \mathcal{N}$.

Appendix C.4.3. Group rationality

Let us consider a coalition of prosumers $\mathcal{S} \in 2^{\mathcal{N}}$, and show that the excess of the coalition $\epsilon_{\mathcal{S}} \left(\pi \left(X^{\mathcal{N}^*}(\mathcal{B}) \right) \right)$ is negative.

By definition of the payment rule and allocation mechanism in (10), the excess $\epsilon_{\mathcal{S}} \left(\pi \left(X^{\mathcal{N}^*}(\mathcal{B}) \right) \right)$ of the coalition can be reformulated as

$$\begin{aligned} \epsilon_{\mathcal{S}} \left(\pi^\lambda \left(X^{\mathcal{N}^*}(\mathcal{B}), \lambda^{\mathcal{N}^*}(\mathcal{B}) \right) \right) &= v^{\mathcal{S}}(\mathcal{B}) - \sum_{j \in \mathcal{S}} \left[\mathcal{P}_j^\lambda \left(X_j^{\mathcal{N}^*}(\mathcal{B}), \lambda^{\mathcal{N}^*}(\mathcal{B}) \right) + \mathcal{F}_j \left(X_j^{\mathcal{N}^*}(\mathcal{B}), Q_j^c \right) - \theta^{\{j\}}(\mathcal{B}) \right] \\ &= \theta^{\mathcal{S}}(\mathcal{B}) - \sum_{j \in \mathcal{S}} \left[\mathcal{P}_j^\lambda \left(X_j^{\mathcal{N}^*}(\mathcal{B}), \lambda^{\mathcal{N}^*}(\mathcal{B}) \right) + \mathcal{F}_j \left(X_j^{\mathcal{N}^*}(\mathcal{B}), Q_j^c \right) \right] \\ &= \sum_{j \in \mathcal{S}} \left[u_j \left(X_j^{\mathcal{S}^*}(\mathcal{B}), \lambda^{\mathcal{S}^*}(\mathcal{B}), \mathcal{B} \right) - u_j \left(X_j^{\mathcal{N}^*}(\mathcal{B}), \lambda^{\mathcal{N}^*}(\mathcal{B}), \mathcal{B} \right) \right]. \end{aligned} \tag{C.13}$$

Outcomes of the mechanism in the grand-coalition \mathcal{N} and the coalition $\mathcal{S} \in 2^{\mathcal{N}}$ are denoted by $(X^{\mathcal{N}^*}(\mathcal{B}), \lambda^{\mathcal{N}^*}(\mathcal{B}))$ and $(X^{\mathcal{S}^*}(\mathcal{B}), \lambda^{\mathcal{S}^*}(\mathcal{B}))$, respectively. As discussed above, these optimal solutions of the convex energy management problem (7) and their associated dual solutions are also Nash equilibriums of the equilibrium problems $Eq.^{\mathcal{N}}$ and $Eq.^{\mathcal{S}}$, respectively. By definition of a Nash equilibrium, and under the assumption of perfect competition, it follows that

$$u_j \left(X_j^{\mathcal{N}^*}(\mathcal{B}), \lambda^{\mathcal{N}^*}(\mathcal{B}) \right) = \max_{X_j \in \mathcal{K}_j^{\mathcal{N}}} u_j \left(X_j, \lambda^{\mathcal{N}^*}(\mathcal{B}) \right), \quad \forall j \in \mathcal{N}. \tag{C.14}$$

Furthermore, for any prosumer $j \in \mathcal{S}$, $X_j^{\mathcal{S}^*} \in \mathcal{K}_j^{\mathcal{N}}$, which implies that

$$u_j \left(X_j^{\mathcal{N}^*}(\mathcal{B}), \lambda^{\mathcal{N}^*}(\mathcal{B}) \right) \geq u_j \left(X_j^{\mathcal{S}^*}(\mathcal{B}), \lambda^{\mathcal{N}^*}(\mathcal{B}) \right), \quad \forall j \in \mathcal{S}. \tag{C.15}$$

By replacing these inequalities in the expression of the excess of the coalition in (C.13), it results that this excess is negative. Hence, we have proved that under the assumption of perfect competition, the allocation mechanism π^λ respects the group rationality. Along with the efficient allocation property, it results that this is a core-selecting mechanism, under the assumption of perfect competition

Appendix D. Case study setup

This section details the setup of the case study used in Section 5.

Table D.5: Preferences: Technical parameters of the assets and building of each prosumer.

		Christos	Anna	Vladimir	Andrea
T^{set}	(°C)	20	20	20	20
\bar{u}^{up}	(°C)	1	1	0	1
\bar{u}^{down}	(°C)	1	1	0	1
c^{up}	(€/°C)	0.001	0.001	-	0.001
c^{down}	(€/°C)	0.01	0.01	-	0.01
\bar{L}^{HP}	(kW)	-	10	-	-
COP^{HP}	-	2.5	-	-	-
$\bar{en}^{\text{E}} / en^{\text{H},0}$	(kWh)	5 / 2.5	-	-	-
$\bar{ch}^{\text{E}} / \bar{dis}^{\text{E}}$	(kW)	2 / 2	-	-	-
$\rho^{\text{dis}^{\text{E}}} / \rho^{\text{ch}^{\text{E}}}$	-	1.1 / 0.9	-	-	-
$\bar{en}^{\text{H}} / en^{\text{H},0}$	(kWh)	-	2.5	-	-
$\bar{ch}^{\text{H}} / \bar{dis}^{\text{H}}$	(kW)	-	2 / 2	-	-
$\rho^{\text{dis}^{\text{H}}} / \rho^{\text{ch}^{\text{H}}}$	-	-	1.1 / 0.9	-	-
\bar{f}^{E}	(kW)	5	5	5	5
\bar{f}^{H}	(kW)	5	5	5	5
$\bar{b}^{\text{E}}, \bar{s}^{\text{E}}$	(kW)	5	5	5	5
$\bar{b}^{\text{H}}, \bar{s}^{\text{H}}$	(kW)	5	5	5	5
α^1	-	1.0062	1.0062	1.0062	1.0062
α^2	-	0.0036	0.0036	0.0036	0.0036
α^3	(0^{-5})	6.17	6.17	6.17	6.17
β^1	-	0.0011	0.0011	0.0011	0.0011
β^2	-	1.0021	1.0021	1.0021	1.0021

Furthermore, the outdoor temperatures T^e and dynamic technical parameters α^0 and β^0 of the buildings are assumed identical for all the buildings in the energy community, and represented in Figure D.3 over all hours of the day.

For the sake of simplicity, solely space heating loads are considered flexible. Table D.6 illustrates the temperature preferences of each prosumer and the cost for deviating from the temperature set-point, which are considered constant over all hours of the day.

Table D.6: Preferences: Temperature preferences and utilities.

		Christos	Anna	Vladimir	Andrea
T^{set}	(°C)	20	20	20	20
\bar{u}^{up}	(°C)	1	1	0	1
\bar{u}^{down}	(°C)	1	1	0	1
c^{up}	(€/°C)	0.001	0.001	-	0.001
c^{down}	(€/°C)	0.01	0.01	-	0.01

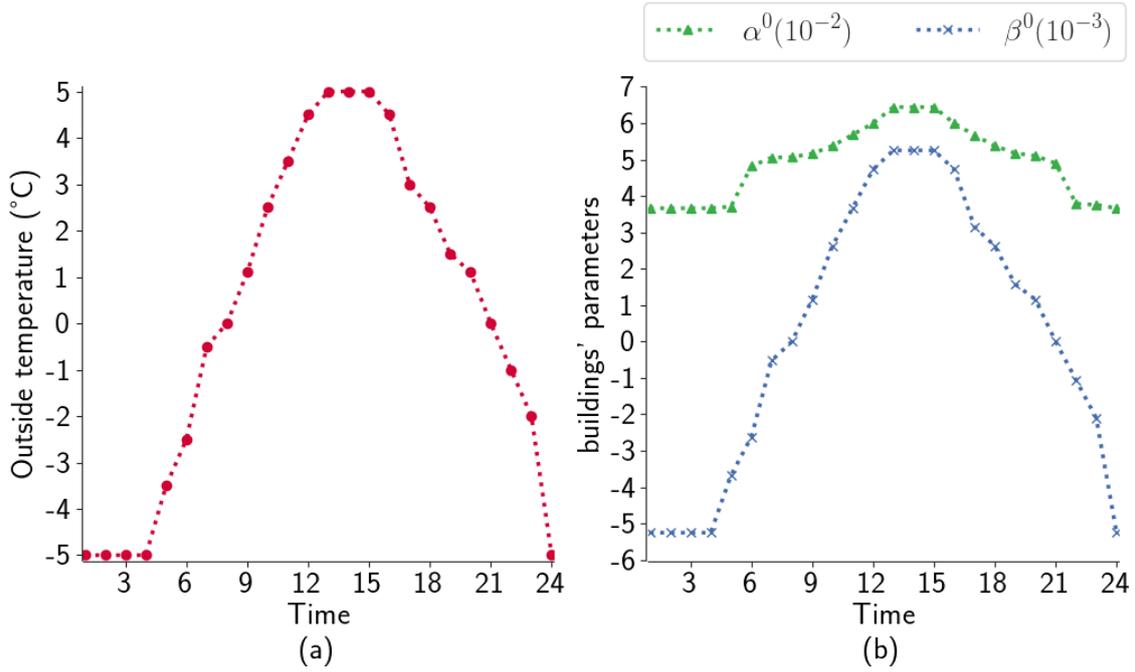


Figure D.3: (a) Outdoor temperatures T^e , and (b) technical parameters α^0 and β^0 of the buildings in the energy community.

Additionally, Figures D.4(a) and D.4(b) illustrate the inflexible electricity and hot water loads of each prosumer over all hours of the day. The electricity production from solar panels belonging to Christos is considered perfectly known, and illustrated in Figure D.4(c) over all hours of the day.

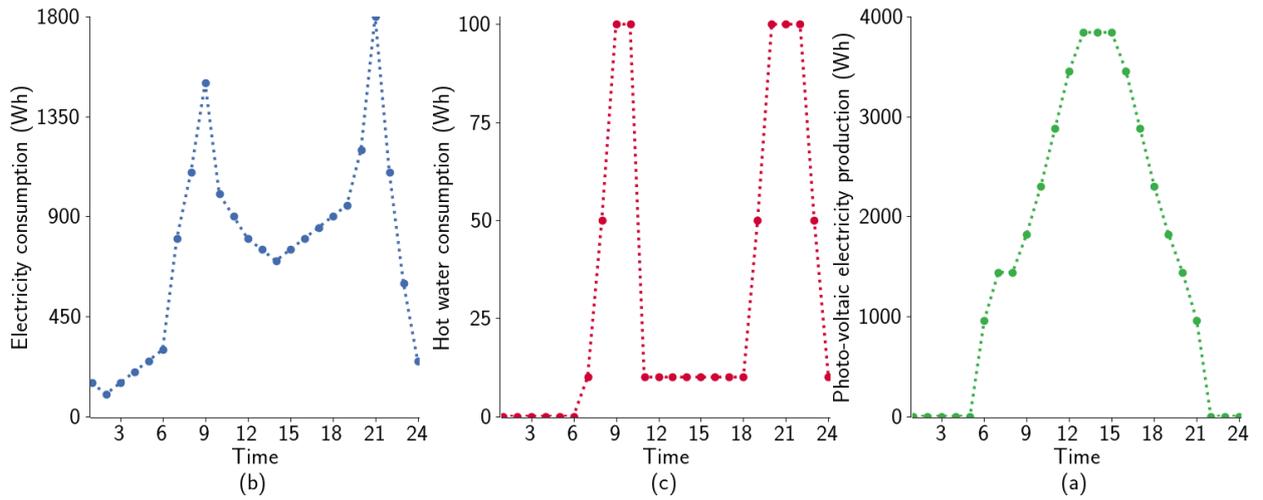


Figure D.4: Inflexible (a) electricity from electrical appliances L^E , and (b) hot water load L^{HW} of each prosumer in the energy community, and (c) photo-voltaic electricity production \overline{Ph}^{ENR} from Christos.

Finally, prosumers can import or export electricity and heat from the grid at an hourly tariff,

as illustrated in Figures D.5(a) and D.5(b).

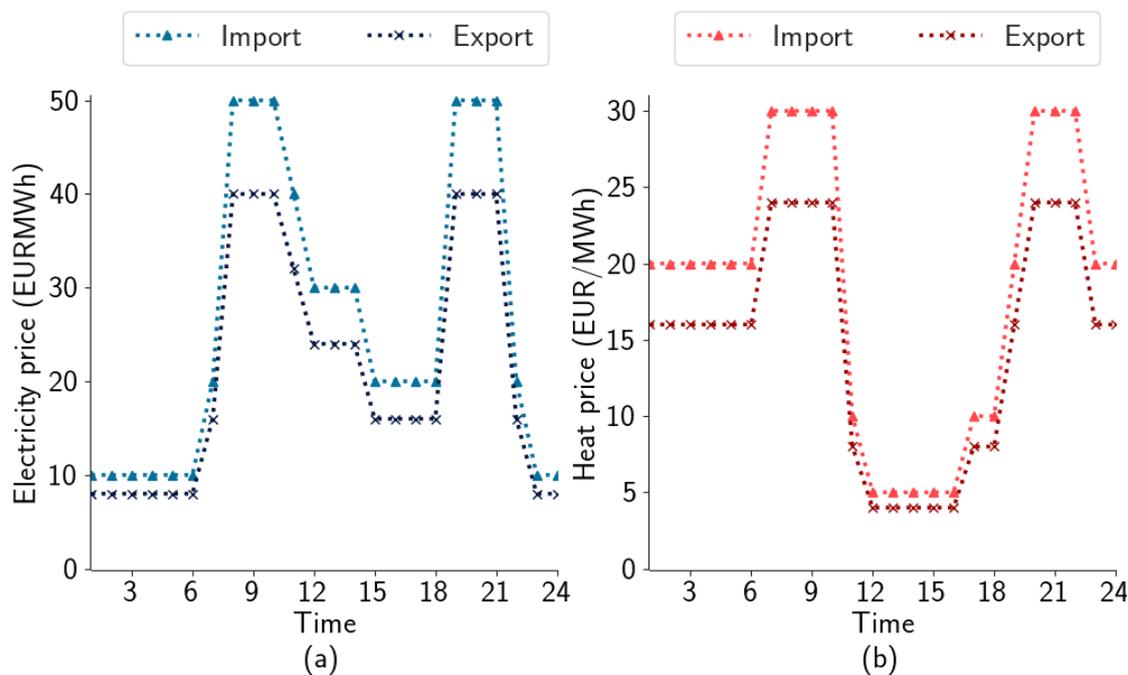


Figure D.5: Hourly tariffs for exchanges with the (a) electricity and (b) heat grids.

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